# A CLOSED $(n+1)$-CONVEX SET IN $R^{2}$ IS A UNION OF $n^{6}$ CONVEX SETS 

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ABSTRACT
It is shown that if a closed set $S$ in the plane is $(n+1)$-convex, then it has no more than $n^{4}$ holes. As a consequence, it can be covered by $\leqq n^{6}$ convex subsets. This is an improvement on the known bound of $2^{n} \cdot n^{3}$.

## §0. Introduction

0.1 . Definitions.
$S$ - a subset (usually closed) of $\mathbf{R}^{d}$.
ker $S$ - the convex kernel of $S$, is the subset of all points of $S$ in relation to which $S$ is star-like. ker $S$ is always convex.

When $S$ is closed, $\operatorname{ker} S$ is also closed.
$G(S)$ - the graph of non-seeing associated with $S$, i.e. the graph whose vertices are the points of $S$, and whose edges connect exactly the pairs of points $a, b \in S$ s.t. $[a, b] \not \subset S$.

Visual Independency - a subset $F$ of $S$ is called visually independent if no two of its points see each other in $S$ (that is, the interval connecting them is not contained in $S$ ).
$\alpha(S)$ - the degree of visual independence of $S$, is the supremum of cardinalities of the visually independent subsets of $S$. Caution: attention should be paid to whether the supremum is obtained or not in the case $\alpha(S)$ is an infinite cardinal. When $\alpha(S)=n<\mathcal{\aleph}_{0}$ we say that $S$ is
( $n+1$ )-convex, as in any subset of $S$ of size $n+1$ there are two points that see each other.

[^0]$\beta(S)$ - the chromatic number of $G(S)$.
$\gamma(S)$ - the minimal cardinal $k$ such that $S$ is the union of $k$ convex sets.
Fact. For any $S, \alpha(S) \leqq \beta(S) \leqq \gamma(S)$.
Proof. Suppose there is a visually independent subset $F$ of $S$ of size $m$. Then its points are the vertices of a complete subgraph of size $m$ of $G(S)$. Therefore the chromatic number of $G(S)$ is at least $m$. This establishes the first inequality. For the second, suppose that $\left\langle C_{i} \mid i<\lambda\right\rangle, \lambda$ a cardinal, is a sequence of convex sets, such that $\bigcup_{i<\lambda} C_{i}=S$. By induction define $B_{i}=\bigcup_{j<i} C_{j}$. Now colour each $B_{i+1}-B_{i}$ with $f_{i},\left\langle f_{i} \mid i<\lambda\right\rangle$ being a sequence of distinct colours. As each $C_{i}$ is convex, this is a valid colouring.
We concern ourselves here with the question: how do restrictions on $\alpha(S)$ and $\beta(S)$ influence $\gamma(S)$, namely, what upper bounds in terms of $\alpha(S)$ and $\beta(S)$ can be put on $\gamma(S)$ ?

Early work in this direction is found in McKinney [3], who proved that for closed $S, \beta(S)=2$ implies $\gamma(S)=2$ and $\beta(S)=3$ implies $\gamma(S)=3$. The pentagonal star shows that $\alpha(S)=2$ does not imply $\gamma(S)=2$.

From now on, $S$ is always a closed subset of the plane. Valentine proved in [4] that for such $S, \alpha(S)=2$ implies $\gamma(S) \leqq 3$. Further progress was made by Eggleston, who proved in [2] that for compact $S$ a finite $\alpha(S)$ implies a finite $\gamma(S)$. The next progress was made by Breen and Kay in [1]. They set a bound of order $m^{3} \cdot 2^{m}$ on $\gamma(S)$ - for $S$ having a finite $\alpha(S)=m$. This bound was reduced to $k \cdot 2^{m}$ ( $k$ a constant) by M. Perles.
The objective of this paper is to establish the bound of $\alpha(S)^{6}$ for closed $S$ in $\mathbf{R}^{2}$ with finite $\alpha(S)$.

Breen and Kay have managed to prove that $\gamma(S)=\alpha(S)$ for $S$ which is supported by a line $H$, namely, is contained in the closed half-plane defined by $H$, and which is star-like in relation to a point $p$ on $H$. So a bound of $2 \cdot \alpha(S)$ follows immediately for star-like $S$ by slicing $S$ through the point in relation to which it is star-like. By the proof of Breen and Kay, for a simply connected set $S$ with $\alpha(S)=m, \gamma(S) \leqq m^{2}$. Further, when a set $S$ has a finite number of holes, it can be sliced by a finite number of lines, one line through each hole, into a finite number of simply connected sets, the degree of visual independence of each being not greater than the original $\alpha(S)$. The exponential factor in the bound of Breen and Kay comes in when trying to estimate the number of holes in a set $S$ with a finite $\alpha(S)$ in terms of $\alpha(S)$.

The bound of $\alpha(S)^{6}$ will follow from the proof of Breen and Kay once a bound of $\alpha(S)^{4}$ is obtained for the number of holes in $S$ : Slice the set to $m^{4}$
simply connected subsets, and cover each by $m^{2}$ convex subsets. A bound of $m^{8}$ on the number of holes was obtained by $S$. Shelah. It was further reduced to $m^{4}$ by M. Perles.
§1. A bound on the number of holes for a set $S$ with $\alpha(S)$ finite
The fixed assumptions in this section are that $S$ is a closed subset of the plane, and that $\alpha(S)=m$ is a natural number.
1.1. Definition. A hole in $S$ is a bounded connected component of the complement of $S$.
1.2. Theorem. For $S$ as above, namely a closed subset of the plane with $\alpha(S)=m$, the number of holes in $S$ does not exceed $m^{4}$.

Proof. We begin by analysing the structure of $K:=\mathrm{cl}(\operatorname{conv}(H))$, where $H$ is a hole of $S$. We first note that $K=\operatorname{cov}(\mathrm{cl}(H))$.

Next we have:
(i) $H \subset \operatorname{Int}(K)$,
(ii) every extremal point of $K$ belongs to the boundary of $H$,
(iii) if $a, b$ are extremal points of $K$ such that $(a, b) \subset \operatorname{Int}(K)$, then $(a, b)$ is not included in $S$.
1.3. Fact. (i) is obvious, and (ii) follows from what is noted above. To see (iii) assume that $(a, b)$ is in $\operatorname{Int}(K)$, so dividing $\operatorname{Int}(K)$ into two open sets. As $K$ is the convex hull of its extremal points, there must be an extremal point of $K$ on each side of $[a, b]$ (otherwise $K$ would be limited to one side). As from (ii) these points are on the boundary of $H$, there are two points of $H$ "near" them, namely, also on different sides of $[a, b]$. As $H$ is open and connected, it is arcwise connected, so an arc connecting these points must intersect $(a, b)$ - necessarily at a point of $H$.

An immediate corollary from (iii) is that there are at most $2 \cdot m+1$ extremal points of $K$ (where $m=\alpha(S)$ ), for otherwise arrange $2 \cdot m+2$ extremal points clockwise on $\operatorname{bd}(H)$ and get a contradiction to ( $m+1$ )-convexity of $S$ by considering the set of points with even index: they do not see each other because of (iii). This corollary implies that $K$ is a polygon.

Let $H_{1}, H_{2}, \ldots, H_{N}$ be a list of $N=m^{4}+1$ different holes of $S$. We intend to derive a contradiction to $(m+1)$-convexity. Our next step is dedicated to showing that we may assume that for two different holes from the list, $H_{i}$ and $H_{j}$, the different respective polygons $K_{i}$ and $K_{j}$ have no vertex in common. So
for each $i$ choose $z_{i} \in H_{i}$, and let $\varepsilon$ be such that for all $i$ the closed disk $B\left[z_{i}, 2 \cdot \varepsilon\right]$ is included in $H_{i}$. Consider $S^{*}=S+B[0, \varepsilon]$ :
(i) $S^{*}$ is closed.
(ii) $\alpha\left(S^{*}\right) \leqq \alpha(S)$.
(iii) $S^{*}$ has among its holes $N$ holes $H_{1}^{*}, \ldots, H_{N}^{*}$ of $S^{*}$ with $z_{i} \in H_{i}^{*}$.
(iv) When $i<j, K_{i}^{*}$ and $K_{j}^{*}$ have no common vertex.
(i) follows from $S^{*}$, being the addition of a closed and a compact set. To prove (ii) suppose $a_{i}^{*}=a_{i}+u_{i}, 0<i \leqq m+1$ are $m+1$ distinct points of $S^{*}$ with $a_{i} \in S$ and $u_{i} \in B[0, \varepsilon]$. From (m+1)-convexity of $S$, without loss of generality assume $a_{1}$ and $a_{2}$ see each other in $S$. Since $\left[a_{1, a 2}\right] \subset S$, $\left[a_{1}, a_{2}\right]+B[0, \varepsilon] \subset S^{*}$. But $\left[a_{1}, a_{2}\right]+B[0, \varepsilon]$ is a convex set with $a_{1}, a_{2}$ in it, so $\left[a_{1}^{*}, a_{2}^{*}\right] \subset S^{*}$. Now for (iii): from the choice of $\varepsilon$ it is clear that $z_{i}$ is not covered by $S^{*}$, and that the connected component of $z_{i}$ in the complement of $S^{*}$ is bounded. Let $H_{i}^{*}$ be the connected component of $z_{i}$ in the complement of $S^{*}$. Lastly, (iv) follows by combining the facts that the vertices of $K_{i}^{*}$ are on the boundary of $H_{i}^{*}$, and that boundaries of different $H_{i}^{* ' s}$ are disjoint.
By replacing $S$ with $S^{*}$, if necessary, we may assume that our $N$ holes $H_{i}$ are such that their respective $K_{i}$ 's are polygons with no vertices in common, and so we do from now on.

Next, assume (by rotating the axes, if necessary) that for any two different vertices $v, v^{\prime}$ from the set of all vertices of all $K_{i}^{\prime}$ 's the segment $\left(v, v^{\prime}\right)$ is not parallel to the $y$-axis. So a single leftmost vertex of each $K_{i}$ is well defined. Rearrange the holes by increasing the order of the $x$-coordinate of the leftmost vertex.
We summarize our assumptions:
(i) $H_{0}, \ldots, H_{N}$ are $m^{4}+1$ holes of $S$;
(ii) $K_{i}=\operatorname{con}\left(\mathrm{cl}\left(H_{i}\right)\right)$ is a polygon;
(iii) $i<j$ implies $K_{i}$ and $K_{j}$ have no vertex in common;
(iv) each $K_{i}$ has a leftmost vertex $z_{i}=\left\langle x_{i}, y_{i}\right\rangle$, and $i<j$ implies $x_{i}<x_{j}$;
(v) $z_{i}$ belongs to the boundary of $H_{i}$.

We intend to associate with each hole $H_{i}$ a ray $R_{i}$ and two segments $J_{i}^{+}, J_{i}^{-}$. To do so we must first recall
1.4. Fact. If $S$ is closed in the plane and $\alpha(S)<\infty$, then $S$ is locally star-like in relation to every point of $S$.

Proof. Suppose the property fails for point $w$ in $S$. That is, for each neighbourhood $B$ of $w, S \cap B$ fails to be star-like in relation to $w$. Define by
induction a sequence $\left\langle x_{n} \mid n<\infty\right\rangle$ of visually independent points of $S$ monotonically converging to $w$ and such that no $x_{n}$ see $w$, as follows. Let $x_{0} \in S$ be a point which does not see $w$. It must exist, or $S$ would be star-like in relation to $w$. Suppose $x_{0}, \ldots, x_{n-1}$ are defined. Because $S$ is closed, there is an open neighbourhood $B$ of $w$ which all of the defined $x$ 's do not see. Utilize the fact that $S \cap B$ is not star-like to choose $x_{n} \in S \cap B$ such that $x_{n}$ does not see $w$. The sequence we have constructed contradicts the finiteness of $\alpha(S)$, thus proving our fact.

To simplify notation, let us describe the definition of the ray $R$ and the segments $J^{+}, J^{-}$for one hole $H$ from our list, where $H$ has convex closure $K$ and where $z_{0}=\left\langle x_{0}, y_{0}\right\rangle$ is a leftmost vertex of $H$. The definition is identical for all $H_{i}$ 's.
Let $h>0$ be a small real number. We define the box

$$
P(h)=\left\{\langle x, y\rangle\left|x_{0}<x<x_{0}+h,\left|y-y_{0}\right|<h\right\} .\right.
$$

Choose $h_{0}$ so small that $S \cap P(h)$ is star-like in relation to $z_{0}$. This is possible because of 1.4. For each $0<h<h_{0}$ define

$$
\Sigma(h)=\left\{\sigma \mid\left\langle x, y_{0}\right\rangle+h \cdot\langle 1, \sigma\rangle \in H\right\},
$$

where $\Sigma(h)$ is an open set in the line $L(h)=\left\{\langle x, y\rangle \mid x=x_{0}+h\right\}$. For $0<h \leqq h_{0}, \Sigma(h)$ is not empty, for if it were empty for some such $h$, the line $L(h)$ would divide $H$ into two connected components, contrary to its definition. We also prove now

### 1.5. Claim. If $0<h^{\prime}<h \leqq h_{0}$ then $\Sigma\left(h^{\prime}\right) \subseteq \Sigma(h)$.

Proof. Let $\sigma \in \Sigma\left(h^{\prime}\right)$. This is to say that $z_{0}+h^{\prime} \cdot\langle 1, \sigma\rangle \in H$. We have to show that $\sigma \in \Sigma(h)$. If this were not the case, we would have the point $z_{0}+h \cdot\langle 1, \sigma\rangle \in S \cap P\left(h_{0}\right)$. But then from our choice of $h_{0}$ (which assures that the $S \cap P\left(h_{0}\right)$ is star-like in relation to $\left.z_{0}\right)$ also $z_{0}+h^{\prime} \cdot\langle 1, \sigma\rangle$ would be in $S$-a contradiction. This proves the claim.

From 1.5 and the fact that each $\Sigma(h)$ is not empty, it follows by compactness that the following is not empty:

$$
\bigcap_{0<k \leq h_{0}} \operatorname{cl}(\Sigma(h)) .
$$

So let us choose a point $\sigma_{0}$ from this non-vacuous intersection, and define the ray $R=\left\{z_{0}+t \cdot\left\langle 1, \sigma_{0}\right\rangle \mid t>0\right\}$. We also define $\sigma_{0}=\inf \left\{\Sigma\left(h_{0}\right)\right\}$ and $\sigma^{+}=$
$\sup \left\{\Sigma\left(h_{0}\right)\right\}$ and define the segments $J_{-}=\left\{z_{0}+h \cdot\left\langle 1, \sigma_{-}\right\rangle \mid 0<h \leqq h_{0}\right\}$ and $J^{+}=\left\{z_{0}+h \cdot\left\langle 1, \sigma^{+}\right\rangle \mid 0<h \leqq h_{0}\right\}$. Note that one of the segments $J^{+}, J_{-}$may lie on $R$.

We make the same definitions as above for each hole in our list, but, still for simplicity of notation, let us concentrate on a single hole $H$. We observe that since for every $0<h<h_{0}, \sigma_{0} \in \operatorname{cl}(\Sigma(h))$, either
(a) $(\sigma, \sigma+\varepsilon) \subseteq \Sigma(h)$ for some $\varepsilon>0$ or
(b) $(\sigma, \sigma-\varepsilon) \subseteq \Sigma(h)$ for some $\varepsilon>0$.

An argument similar to the argument we used in 1.5 shows
1.6. Fact. If (a) holds for $\varepsilon$ and $h$ and $h<h^{\prime} \leqq h_{0}$, then (a) holds for $\varepsilon$ and $h^{\prime}$; the same for (b).

Now either (a) or (b) must hold for arbitrarily small $h$; therefore 1.6 gives
1.7. Fact. Either
(a) for all $0<h \leqq h_{0}$, (a) holds
or
(b) for all $0<h \leqq h_{0}$, (b) holds.

Let us denote by $R^{+}\left(R^{-}\right)$the open upper (lower) half-plane determined by $R$. A straightforward corollary of 1.7 is
1.8. Corollary. If $\left(a^{\prime}\right)$ holds, then whenever $v$ is a point on $R$ such that $x(v)<h_{0}$, there is an open neighborhood B of v such that $B \cap R^{+} \subseteq H$; the same with $R^{-}$if $\left(\mathrm{b}^{\prime}\right)$ holds.
1.8 intuitively says that there is an open stripe of $H$ either right above or right below $R$ near $z_{0}$.
We now define $Q^{+}$to be the upper right quarter-plane determined by $R$ and $\left\{\langle x, y\rangle \mid x=x_{0}\right\}$ and $Q^{-}$to be the lower right quarter-plane, and we add $R$ to the first in case ( $b^{\prime}$ ) holds, and to the latter otherwise. More precisely, if ( $b^{\prime}$ ) holds then

$$
Q^{+}=\left\{z_{0}+t \cdot\langle 1, \sigma\rangle \mid t>0, \sigma>\sigma_{0}\right\}
$$

and

$$
Q^{-}=\left\{z_{0}+t \cdot\langle 1, \sigma\rangle \mid t>0, \sigma \leqq \sigma_{0}\right\}
$$

and analogously when ( $a^{\prime}$ ) holds. Now we can finally prove our main result.
1.9. Lemma. If $w \in S \cap Q^{+}$then there is an $h_{w}$ such that the sub-segment $\left\{z_{0}+t \cdot\left\langle 1, \sigma_{-}\right\rangle \mid 0<t<h_{w}\right\} \subset J_{-}$is not seen by $w$, and if $w \in S \cup Q^{-}$then
there is an $h_{w}$ such that the sub-segment $\left\{z-0+t \cdot\left\langle 1, \sigma^{+}\right\rangle \mid 0<t<h_{w}\right\}$ of $J_{+}$ is not seen by $w$.


Fig. 1.

Proof. This is easy if one looks at Fig. 1. Suppose ( $a^{\prime}$ ) holds. Let $w \in S \cap Q^{+}$. Denote by $u(h)$, for small enough $h$, the point on $J_{-}$with $x(u)=h$. By connecting $w$ to $u(h)$ we intersect $R$ at the unique point $v(h)$. Clearly, as $h$ tends to 0 , also $x(v(h))$ tends to 0 . So set $h$ small enough that
$x(v(h))$ is smaller than $h(0)$. By 1.8 the segment $\langle w, u(h)\rangle$ passes in an open neighbourhood of $v(h)$ which is in $H$, and, furthermore, the same is true for all $h^{\prime}<h$. Now let $w \in Q_{-}$. If $w$ is not on $R$, the same argument works. If $w$ is on $R$, find $h$ so small that there is a point $v(h)$ on $R$ with a neighborhood in $H$ containing the segment $\langle v(h), v(h)+\langle 0, n)\rangle$. Take the part of $J^{+}$which this segment in $H$ shades from $w$. The case when ( $b^{\prime}$ ) holds is symmetric.

Recall now that we have the definitions and Lemma 1.9 for all the holes in our list. Look at the sequence of $m^{4}+1$ slopes $\left\langle\sigma_{i} \mid i<N\right\rangle$ of the rays $\left\langle R_{i} \mid i<N\right\rangle$. There is either a weakly increasing subsequence of length $m^{2}+1$ or a weakly decreasing such subsequence. Without loss of generality assume that $\left\langle\sigma_{0}, \ldots, \sigma_{M}\right\rangle$ is a weakly increasing sequence, where $M=m^{2}+1$. Observe now the set $\left\{Q_{i}^{+} \mid i<M\right\}$ partially ordered by inclusion. By Dillworth's theorem it has either an antichain of size $m+1$ or a chain of size $m+1$.

So let us first suppose that $Q_{0}^{+}, \ldots, Q_{m}^{+}$forms a chain with respect to inclusion. This means that if $i<j<m+1$ then $z_{j} \in Q_{i}^{+}$. We define now by induction on $i$ a set of $m+1$ visually independent points of $S$ such that each $x_{i} \in J_{-i}$ and $i<j$ implies $x_{i}$ does not see $z_{j}$. By repeated use of the lemma choose $x_{0} \in J_{-0}$ which does not see any of $\left\{z_{j} \mid j>1\right\}$. Suppose that $x_{i}$ were chosen for $i<n \leqq m$. There is a neighborhood of $z_{n}$ which all $x_{i}, i<n$ do not see. Inside this neighourhood find a point $x_{n} \in J_{-n}$. So $x_{0}$ satisfies both requirements. We may choose $x_{m+1}$ to be $z_{m+1}$. The set we have obtained is the desired contradiction to $\alpha(S)=m$.

Next suppose that $Q_{0}^{+}, \ldots, Q_{m}^{+}$forms an antichain with respect to inclusion. This means evidently that $i<j$ implies $z_{j} \in Q_{-j}$. The same inductive process as above works also here. This completes our proof of the bound $m^{4}$ on the number of holes of $S$.

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