



A dividing line within simple unstable theories [☆]

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Abstract

We give the first (ZFC) dividing line in Keisler's order among the unstable theories, specifically among the simple unstable theories. That is, for any infinite cardinal λ for which there is $\mu < \lambda \leq 2^\mu$, we construct a regular ultrafilter \mathcal{D} on λ so that (i) for any model M of a stable theory or of the random graph, M^λ/\mathcal{D} is λ^+ -saturated but (ii) if $Th(N)$ is not simple or not low then N^λ/\mathcal{D} is not λ^+ -saturated. The non-saturation result relies on the notion of flexible ultrafilters. To prove the saturation result we develop a property of a class of simple theories, called Qr_1 , generalizing the fact that whenever B is a set of parameters in some sufficiently saturated model of the random graph, $|B| = \lambda$ and $\mu < \lambda \leq 2^\mu$, then there is a set A with $|A| = \mu$ so that any nonalgebraic $p \in S(B)$ is finitely realized in A . In addition to giving information about simple unstable theories, our proof reframes the problem of saturation of ultrapowers in several key ways. We give a new characterization of good filters in terms of “excellence”, a measure of the accuracy of the quotient Boolean algebra. We introduce and develop the notion of moral ultrafilters on Boolean algebras. We prove a so-called “separation of variables” result which shows how the problem of constructing ultrafilters to have a precise degree of saturation may be profitably separated into a more set-theoretic stage, building an excellent filter, followed by a more model-theoretic stage: building so-called moral ultrafilters

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on the quotient Boolean algebra, a process which highlights the complexity of certain patterns, arising from first-order formulas, in certain Boolean algebras.

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1. Introduction

In 1967 Keisler introduced a framework for comparing the complexity of (countable) first-order theories in terms of the relative difficulty of producing saturated regular ultrapowers. Morley, reviewing the paper [8], wrote that “the exciting fact is that \leq gives a rough measure of the ‘complexity’ of a theory. For example, first-order number theory is maximal while theories categorical in uncountable powers are minimal”.

The only known classes in Keisler's order appear in [Theorem A](#) below.

Summary Theorem A (*Results on classes in Keisler's order*). *It is known that:*

$$\mathcal{T}_1 < \mathcal{T}_2 < \mathcal{T}_3 \cdots \leq \mathcal{T}_{max}$$

where $\mathcal{T}_1 \cup \mathcal{T}_2$ is precisely the class of countable stable theories, and:

- \mathcal{T}_1 , the minimum class, is the set of all T without the finite cover property (so stable), e.g. algebraically closed fields.
- \mathcal{T}_2 , the next largest class, is the set of all stable T with the finite cover property.

Among the unstable theories,

- There is a minimum class \mathcal{T}_3 , which contains the theory of the random graph.
- Among the theories with TP_2 , there is a minimum class \mathcal{T}_* , which contains \mathcal{T}_{feq} .
- There is a maximum class \mathcal{T}_{max} , containing all theories with SOP_3 , thus all linear orders.

However, no model-theoretic identities of unstable classes are known.

Keisler in the fundamental 1967 paper [8] defined the order and showed the existence of minimum and maximum classes, and defined the finite cover property. In 1978, Shelah [18] established the identity of \mathcal{T}_1 and \mathcal{T}_2 , showing that Keisler's order independently detects certain key dividing lines from classification theory. Shelah also proved that the theory of linear order, and more generally *SOP*, belongs to T_{max} , and in 1996 extended this to SOP_3 , see Shelah [21] and Shelah and Usvyatsov [22]. In 2010, Malliaris [13] proved the existence of a minimum class among the TP_2 theories, which contains the theory of a parametrized family of independent equivalence relations. For further details on these results, see the introduction to the authors' paper [15]. The only prior non-ZFC result on Keisler's order was Shelah's result [18, VI.3.10], which implies that if MA and not CH then the random graph is not \aleph_1 -maximal in Keisler's order. Under GCH, results on nonmaximality in a related ordering \leq^* were proved in Džamonja and Shelah [4] and Shelah and Usvyatsov [22], results which are particularly interesting in light of our recent work on Keisler's order and SOP_2 [17].

Recently, there has been substantial progress in understanding the interaction of ultrafilters and theories (Malliaris [10–14], Malliaris and Shelah [15–17]). These results set the stage for our current work.

In this paper we give the first ZFC dividing line among the unstable theories, specifically among the simple unstable theories. Our proof reframes the problem of saturation of ultrapowers in terms of so-called excellence of an intermediate filter and so-called morality of an ultrafilter on the resulting quotient Boolean algebra. We also introduce a property Qr_1 which captures relevant structure of a class of simple theories including the random graph.

Main Theorem. (*Theorem 12.1 below.*) *Suppose λ, μ are given with $\mu < \lambda \leq 2^\mu$. Then there is a regular ultrafilter \mathcal{D} on λ which saturates ultrapowers of all countable stable theories and of the random graph, but fails to saturate ultrapowers of any non-low or non-simple theory.*

The organization of the paper is as follows. Section 2 is an extended overview of our methods and results. Section 3 defines Keisler's order, as well as regular, good, flexible (said of filters) and simple and low (said of theories). Section 4 motivates and defines the notion of *excellence* for a filter. Section 5 deals with the relation of goodness and excellence. Section 6 defines moral ultrafilters and proves the theorem on separation of variables. Section 7 contains the ingredients needed for proving the existence of excellent filters admitting specified homomorphisms. It begins with review of constructions via independent families, introduces some notation needed for the current setting and concludes by proving the two key inductive steps for the existence proof. Section 8 contains the existence proof. Section 9 contains the proof of non-saturation via non-flexibility described above. Section 10 motivates and defines $Qr_1 = Qr_1(T, \lambda, \mu)$, and proves that this holds for the theory of the random graph. Section 11 proves that when $\mu < \lambda \leq 2^\mu$ there is an ultrafilter on $\mathfrak{B}_{2^\lambda, \mu}$ which is moral for any theory for which $Qr_1(T, \lambda, \mu)$. Section 12 contains the statement and proof of the main theorem.

2. Summary of results

To explain our methods, we give here an overview of the main theorems and objects of the paper. This discussion is informal, and many definitions are deferred to later sections.

Convention 2.1. For transparency, all filters are regular (Definition 3.3), and all theories are countable. “Monotonic” means antimonotonic, i.e. $u \subseteq v \implies f(v) \subseteq f(u)$.

2.1. Excellent filters

A key point of leverage in our argument is the development of so-called excellent filters, a notion which gives a new characterization of goodness, [Theorem 5.2](#).

To frame our approach, we briefly discuss good filters and their central role in questions of saturation. Let $N = M^\lambda/\mathcal{D}$ be a regular ultrapower and $p \in S(A)$, $A \subseteq N$, $|A| = \lambda$. Fix in advance some canonical lifting from elements of M^λ/\mathcal{D} to M^λ . We may consider p as being represented by some $f : \mathcal{P}_{\aleph_0}(\lambda) \rightarrow \mathcal{D}$, as follows. Write $p = \{\varphi_i(x, a_i) : i < \lambda\}$ and let $f(u) = \{t < \lambda : M \models \exists x \bigwedge_{i \in u} \varphi_i(x, a_i[t])\}$ (the “Łoś map”). Then $u \in \mathcal{P}_{\aleph_0}(\lambda) \implies f(u) \in \mathcal{D}$ by Łoś’s theorem, f is naturally monotonic, and moreover as \mathcal{D} is regular, we can choose f so that f refines the Łoś map and each $t < \lambda$ belongs to only finitely many of the sets $f(u)$, as spelled out in [Definition 6.8](#), [Convention 6.9](#), [Observations 6.10](#), [6.11](#) below. Thus whether or not the type p is realized in N depends on whether some such distribution f is “multiplicative”: informally, does $t \in f(u)$, $t \in (v)$ imply that $t \in f(u \cup v)$, which entails asking whether the various finite fragments of the type which are witnessed in a given index model have a *common* realization there.

Meanwhile, a filter \mathcal{D} on λ is said to be λ^+ -good if every monotonic $f : \mathcal{P}_{\aleph_0}(\lambda) \rightarrow \mathcal{D}$ has a multiplicative refinement, that is, a function f' so that for all u , $f'(u) \subseteq f(u)$ and for all u, v $f'(u \cup v) = f'(u) \cap f'(v)$. From the point of view of saturation, good ultrafilters are maximally powerful in the sense that if \mathcal{D} is a regular good (i.e. λ^+ -good) ultrafilter on λ and M any model in a countable signature, then M^λ/\mathcal{D} is λ^+ -saturated. It follows from the above discussion that the maximum class in Keisler’s order has a set-theoretic characterization: it is precisely the set of countable theories T so that $M \models T$ and \mathcal{D} regular implies M^λ/\mathcal{D} is λ^+ -saturated iff \mathcal{D} is good. [For an account of this correspondence and of other recent work on Keisler’s order, see [\[15, Sections 1, 4\]](#).] The existence of λ^+ -good ultrafilters on λ is a result of Keisler assuming GCH [\[7\]](#) and of Kunen in ZFC [\[9\]](#), see for instance [\[20, pp. 345–347\]](#).

Now let us motivate a definition of the present paper. To make finer distinctions in ultrafilter construction, we would like a greater degree of precision than is a priori available from the definition of goodness. The issue comes into focus when working with filters rather than ultrafilters:

Remark 1. Let \mathcal{D} be a regular good filter on I and let $\bar{A} = \langle A_u : u \in [\lambda]^{<\aleph_0} \rangle$ be a monotonic sequence of nonzero elements (mod \mathcal{D}) of $\mathcal{P}(I)$, not necessarily a sequence of elements of \mathcal{D} . A priori, goodness of \mathcal{D} will only guarantee multiplicative refinements for monotonic sequences of elements of \mathcal{D} , so is not enough to guarantee a multiplicative refinement for \bar{A} .

Remark 2. Continuing in the context of [Remark 1](#), suppose the image of $\langle A_u : u \in [\lambda]^{<\aleph_0} \rangle \subseteq \mathcal{P}(I)$ in the quotient Boolean algebra $\mathfrak{B} = \mathcal{P}(I)/\mathcal{D}$ is $\bar{\mathbf{a}} = \langle \mathbf{a}_u : u \in [\lambda]^{<\aleph_0} \rangle$, and $\bar{\mathbf{a}}$ has a multiplicative refinement $\langle \mathbf{b}_u : u \in [\lambda]^{<\aleph_0} \rangle$ in \mathfrak{B} . Then \bar{A} will have a refinement \bar{B} which is multiplicative mod \mathcal{D} . That is, $u, v \in [\lambda]^{<\aleph_0} \implies B_u \cap B_v = B_{u \cup v}$ mod \mathcal{D} , which a priori does not imply that an actual multiplicative refinement of \bar{A} exists.

Remark 3. From this and other considerations, one sees that a useful intensification of goodness will be *making the quotient Boolean algebra more precise*. What does this mean? Roughly speaking, that properties of sequences in the quotient Boolean algebra accurately reflect those in $\mathcal{P}(I)$: if a sequence in the quotient Boolean algebra appears to have certain properties, e.g. multiplicativity, then we can indeed pull it back to a multiplicative sequence in $\mathcal{P}(I)$.

Our process of gaining precision will first require [Definitions 4.2, 4.3 and 4.5](#), which are not quoted in this introduction, but allow us to describe a relevant set of Boolean terms Λ . Informally, the idea is that we would like to replace some sequence of elements of $\mathcal{P}(I)$ by a \mathcal{D} -equivalent sequence in such a way that certain sets in the Boolean algebra of elements in the original sequence, which are $\emptyset \bmod \mathcal{D}$, now correspond to sets which are really empty. (We sometimes refer to this as solving equations $\bmod \mathcal{D}$.) However, asking to do this for *all* small sets would be too strong, as explained in [Example 4.8](#). The set of terms Λ captures the right set of “rough edges” which we can trim off without removing too much. And it is indeed rich enough to solve the issues just sketched: see [Claim 4.9](#).

Definition 4.6 (*Excellent filters*). Let \mathcal{D} be a filter on the index set I . We say that \mathcal{D} is λ^+ -excellent when: if $\bar{A} = \langle A_u : u \in [\lambda]^{<\aleph_0} \rangle$ with $u \in [\lambda]^{<\aleph_0} \implies A_u \subseteq I$, then we can find $\bar{B} = \langle B_u : u \in [\lambda]^{<\aleph_0} \rangle$ so that:

- (1) for each $u \in [\lambda]^{<\aleph_0}$, $B_u \subseteq A_u$,
- (2) for each $u \in [\lambda]^{<\aleph_0}$, $B_u = A_u \bmod \mathcal{D}$,
- (3) if $u \in [\lambda]^{<\aleph_0}$ and $\sigma \in \Lambda = \Lambda_{\mathcal{D}, \bar{A}|_u}$, so $\sigma(\bar{A}|_{\mathcal{P}(u)}) = \emptyset \bmod \mathcal{D}$, then $\sigma(\bar{B}|_{\mathcal{P}(u)}) = \emptyset$.

We say that \mathcal{D} is ξ -excellent when it is λ^+ -excellent for every $\lambda < \xi$.

Note: the definition of this set of terms Λ arises naturally from the inductive construction of excellence, see [Claim 7.22](#), and also [Example 4.8](#).

Remark 4. The analysis and definition of excellence will have the following consequences for ultrafilter construction. Once we have a notion of excellent filter, there is a potentially two-stage construction of a given ultrafilter in which we first ensure excellence of some intermediate filter \mathcal{D} , and then move to work directly on the quotient Boolean algebra for the remainder of the construction, leveraging the guarantee that the work on the Boolean algebra will be sufficiently accurate.

This “paradigm shift” is accomplished in [Section 6](#) with [Theorem 6.13](#), also quoted later in this introduction. We have called [Theorem 6.13](#) a separation of variables result. In some sense it allows us to separate the more set-theoretic considerations involved in building an excellent filter from the more model-theoretic considerations involving the complexity of patterns coming from a given formula in certain Boolean algebras $\mathfrak{B}_{2^\lambda, \mu}$.

2.2. Morality and separation of variables

The phenomenon of excellence naturally gives rise to a complementary property we call “morality”, [Definition 6.3](#). Say that an ultrafilter \mathcal{D}_* on a Boolean algebra \mathfrak{B} is moral for a theory T if, roughly speaking, any incidence pattern for T represented in \mathfrak{B} can be resolved (multiplicatively refined) in \mathcal{D}_* . The definition does not rely on the setting of reduced products. Excellence and morality then combine to give saturation in the following way:

Theorem 6.13 (*Separation of variables*). *Suppose that we have the following data:*

- (1) \mathcal{D} is a regular, λ^+ -excellent filter on I ,
- (2) \mathcal{D}_1 is an ultrafilter on I extending \mathcal{D} , and is $|T|^+$ -good,

- (3) \mathfrak{B} is a Boolean algebra,
 (4) $\mathbf{j}: \mathcal{P}(I) \rightarrow \mathfrak{B}$ is a surjective homomorphism with $\mathcal{D} = \mathbf{j}^{-1}(\{1_{\mathfrak{B}}\})$,
 (5) $\mathcal{D}_* = \{\mathbf{b} \in \mathfrak{B}: \text{if } \mathbf{j}(A) = \mathbf{b} \text{ then } A \in \mathcal{D}_1\}$.

Then the following are equivalent:

- (A) \mathcal{D}_* is $(\lambda, \mathfrak{B}, T)$ -moral, i.e. moral for each formula φ of T .
 (B) For any λ^+ -saturated model $M \models T$, M^λ/\mathcal{D}_1 is λ^+ -saturated.

Discussion 2.2. What does [Theorem 6.13](#) accomplish? At first glance, it may appear that we have traded one construction problem (building an ultrafilter on λ) for another (building an ultrafilter on \mathfrak{B}). The gain is revealing a point of leverage which will allow us to separate theories by realizing some types while omitting others. The leverage is provided by the size of a maximal antichain in the quotient Boolean algebra $B(\mathcal{D}) = \mathcal{P}(I)/\mathcal{D}$. By [Theorem 8.1](#), when building excellent filters we are relatively free to modify this quotient Boolean algebra.

Then the strategy is as follows. For non-saturation, we will show that if $CC(B(\mathcal{D})) = \mu^+ < \lambda^+$, no subsequent ultrafilter can be flexible, and then apply our prior work. For saturation, we will show that when $\mu < \lambda \leq 2^\mu$ this need not prevent saturation of the random graph.

Sections 7–8 contain a proof of the existence of excellent filters meeting the requirements of [Theorem 6.13](#). [Theorem 8.1](#), which we now quote, is more general than what is needed for the application to [Theorem 12.1](#). In that specific case, one could use [Theorem 5.2](#) showing the equivalence of excellent and good, and then build \mathcal{D} to be a good regular filter on λ so that $(I, \mathcal{D}, \mathcal{G})$ is a (λ, μ) -good triple. The more general result reflects the fact that the framework of [Theorem 6.13](#) is a main contribution of the paper; we make significant further use of this framework, for a wider range of Boolean algebras, in work in preparation. Moreover, note that the inductive [Claim 7.22](#) of [Theorem 8.1](#) clearly shows the naturalness of the definition of Λ from [Definition 4.5](#), and thus in some sense, its optimality.

Theorem 8.1 (*Existence theorem*). *Let $\mu \leq \lambda$, $|I| = \lambda$ and let \mathfrak{B} be a μ^+ -c.c. complete Boolean algebra of cardinality $\leq 2^\lambda$. Then there exists a regular excellent filter \mathcal{D} on I and a surjective homomorphism $\mathbf{j}: \mathcal{P}(I) \rightarrow \mathfrak{B}$ so that $\mathbf{j}^{-1}(1) = \mathcal{D}$.*

[Theorem 8.1](#) requires several lemmas and some notation, but otherwise proceeds smoothly. Briefly, we need to accomplish two things: first, to “solve” all instances of excellence, and second to ensure the existence of the homomorphism \mathbf{j} . We begin with a regular filter \mathcal{D}_0 and two disjoint independent families, $\mathcal{F} \subseteq {}^I\lambda$ of cardinality 2^λ , and $\mathcal{G} \subseteq {}^I2$ of cardinality $|\mathfrak{B}|$. We extend to a second filter \mathcal{D}_1 in which $\{\mathbf{b}_\gamma: \gamma < |\mathfrak{B}|\}$ and $\{g_\gamma^{-1}(1): \gamma < |\mathcal{G}|\}$ “look alike” in the sense of [Definition 7.14](#). We then build the filter \mathcal{D} by induction on $\alpha < 2^\lambda$ while respecting this background correspondence, consuming the functions \mathcal{F} while giving no further constraints on \mathcal{G} . At odd successor stages, we ensure that a given subset of I will have an appropriate homomorphic image via [Lemma 7.21](#). At even stages, we solve instances of excellence using [Claim 7.22](#).

2.3. Non-saturation

The non-saturation results arise via the notion of *flexible* filter, introduced in Malliaris [\[10\]](#). By Malliaris [\[10\]](#), flexibility is a necessary condition for an ultrafilter to saturate some non-low

theory. By Malliaris [13] for the case of TP_2 , and Malliaris and Shelah [17] for the case of SOP_2 , flexibility is a necessary condition for an ultrafilter \mathcal{D} to saturate some non-simple theory. We then adapt a proof of Shelah [20] originally stated for goodness to show that when the c.c. of the quotient Boolean algebra falls at or below the size of the index set, no subsequent ultrafilter will be flexible, and thus every subsequent ultrafilter will fail to saturate any non-simple or non-low theory:

Corollary 9.9 (*Non-flexibility, thus non-saturation*). *Let $\mu < \lambda$ and let \mathcal{D} be a regular λ^+ -excellent filter on λ given by Theorem 8.1 in the case where $\mathbf{j}(\mathcal{P}(I)) = \mathfrak{B}_{2^\lambda, \mu}$ (so has the μ^+ -c.c.). Then no ultrafilter extending \mathcal{D} , built by the methods of independent functions, is λ -flexible.*

Note that the class of simple non-low theories is nonempty, as discussed in 3.9 below.

2.4. Saturation

The saturation results arise from a property of the random graph used by Shelah in [20, Theorem VI.3.10]. This key property, which follows from Engelking and Karłowicz [5], is that if $\mu < \lambda \leq 2^\mu$, $A \subseteq \mathfrak{C}_{T_{rg}}$, $|A| \leq \lambda$ then for some $B \subsetneq \mathfrak{C}_{T_{rg}}$, $|B| = \mu$ we have that every nonalgebraic $p \in S(A)$ is finitely realized in B . That is, the nonalgebraic types over a given set of size λ can be finitely realized in a set of strictly smaller size; see Section 10 below for a proof. Note that by [19], every simple theory T has a related, though weaker, property.

We develop a generalization of this property appropriate for our context, called Qr_1 . Informally, $\text{Qr}_1(T, \lambda, \mu)$ says of T that any monotonic sequence from $\mathcal{P}_{\aleph_0}(\lambda)$ into the given Boolean algebra $\mathfrak{B} = \mathfrak{B}_{2^\lambda, \mu}$, which accurately “represents” a pattern from the background theory T , can be approximated by μ multiplicative sequences. This property may be thought of as describing genericity, in the sense of the independence property; it is naturally orthogonal, in a non-technical sense, to the phenomenon of dividing, in which the many instances of the formula φ are “spread out” and do not admit common realizations. In Section 11 we show that Qr_1 holds of the random graph:

Lemma 10.9 (*Qr_1 for the random graph*). *Let T be the theory of the random graph. Then $\text{Qr}_1(T, \lambda, \mu)$.*

Briefly, to prove Lemma 10.9 begin with a “possibility pattern”, the avatar of a type. Choose a complete subalgebra of \mathfrak{B} on which this sequence is supported, and which itself is covered by few ultrafilters. Roughly speaking, we look at what happens to the type under each such ultrafilter (we define a function which records how the parameters collide) and choose a small dense subset of types over this “collapsed” parameter set. Since types over the “collapsed” sets have parameters which are everywhere distinct, they will always be realized. Now to find a “cover” of a given finite fragment of the original type, we can first choose an ultrafilter in which its finitely many parameters remain distinct, then choose an appropriate member of the dense set of realized types.

In Section 11 we apply Lemma 10.9 to prove the existence of an ultrafilter \mathcal{D}_* on $\mathfrak{B}_{2^\lambda, \mu}$ which is moral for a class of theories including the theory of the random graph:

Theorem 11.1 (*The moral ultrafilter*). *Suppose $\mu < \lambda \leq 2^\mu$ and let $\mathfrak{B} = \mathfrak{B}_{2^\lambda, \mu}$. Then there is an ultrafilter \mathcal{D}_* on \mathfrak{B} which is moral for all countable theories T so that $\text{Qr}_1(T, \lambda, \mu)$. In particular, \mathcal{D}_* is moral for all countable stable theories and for the theory of the random graph.*

Finally, we combine these results to prove the main theorem:

Theorem 12.1 (*The dividing line*). *Let $\mu < \lambda \leq 2^\mu$. Then there is a regular ultrafilter \mathcal{D} on λ so that:*

- (1) *for any countable theory T so that $\text{QR}_1(\lambda, \mu, T)$ and $M \models T$, M^λ/\mathcal{D} is λ^+ -saturated,*
- (2) *in particular, when T is stable or T is the theory of the random graph, M^λ/\mathcal{D} is λ^+ -saturated,*
- (3) *for any non-low or non-simple theory T and $M \models T$, M^λ/\mathcal{D} is not λ^+ -saturated.*

Thus there is a dividing line in Keisler's order among the simple unstable theories.

Discussion 2.3. Following our work here, to separate theories T, T' in Keisler's order it is therefore sufficient to find a pair $(\mathfrak{B}, \mathcal{D}_*)$ s.t. \mathfrak{B} is a λ^+ -c.c. complete Boolean algebra of cardinality $\leq 2^\lambda$ and \mathcal{D}_* an ultrafilter on \mathfrak{B} which is (λ, T) -moral but not (λ, T') -moral. Note that this gives natural new “outside” definitions of classes of first-order theories in terms of whether e.g. every ultrafilter on a given Boolean algebra is moral for T . Do such classes have nice inside definitions?

3. Basic definitions

Here we define Keisler's order, the properties (of filters) regular and good, and the properties (of theories) simple and low. A fairly extensive discussion of Keisler's order, including an overview of relevant recent work [10–16], can be found in Malliaris and Shelah [15]. For an accessible survey of simplicity, including results on Boolean algebras of nonforking formulas in simple theories from [19], see Grossberg, Iovino and Lessmann [6]. For further background on ultrafilters and ultrapowers, see [20, Chapter VI], [8,10].

We concentrate on regular ultrafilters which, by [Theorem B](#) below, focus attention on the theory rather than the choice of index models.

Convention 3.1. All ultrafilters in this paper, unless otherwise stated, are regular, [Definition 3.3](#) below. T ranges over complete countable first-order theories, though we indicate some extensions to uncountable languages.¹ We use λ to denote an infinite cardinal. I is an index set of cardinality λ , though this is usually stated.

By “ \mathcal{D} saturates T ” we will always mean: \mathcal{D} is a regular ultrafilter on I , T is a countable complete first-order theory and for any $M \models T$, we have that M^I/\mathcal{D} is λ^+ -saturated, where $\lambda = |I|$.

Remark 3.2. We make no global assumptions on λ other than $\lambda \geq \aleph_0$, and we do not require λ to be regular. In the ultrafilter constructions we carry out, this is always enough to guarantee existence of an independent family of functions $f : \lambda \rightarrow \lambda$, of size 2^λ , see [5]. If we had wanted the family to be independent in a stronger way, e.g. asking that any $< \kappa$ functions simultaneously achieve their assigned values on a nonempty set (which we do not use in the present argument), then we would need $\lambda^{<\kappa} = \lambda$. See [20, Appendix, Theorem 1.5].

¹ Namely, the statements of several key theorems include the condition “ \mathcal{D} is $|T|^+$ -good”. This will be automatically satisfied in our main case of interest, T countable (see [20, Claim 2.1, p. 334]). Otherwise, this extra condition puts no real burden on the proofs and will allow for easier quotation later on.

Definition 3.3. A filter \mathcal{D} on an index set I of cardinality λ is said to be λ -regular, or simply regular, if there exists a λ -regularizing family $\langle X_i : i < \lambda \rangle$, which means that:

- for each $i < \lambda$, $X_i \in \mathcal{D}$, and
- for any infinite $\sigma \subset \lambda$, we have $\bigcap_{i \in \sigma} X_i = \emptyset$.

Equivalently, for any element $t \in I$, t belongs to only finitely many of the sets X_i .

To see that regular ultrafilters on infinite cardinals always exist, fix some $f : \mathcal{P}_{\aleph_0}(\lambda) \rightarrow \lambda$. Then $\{\{s \in \lambda : \eta \in f^{-1}(s)\} : \eta < \lambda\}$ can be extended to a filter on λ which will be regular, see e.g. [3].

By the next theorem, in our context, saturation of the ultrapower does not depend on the choice of index model within its elementary class. Thus the restriction to regular filters justifies the quantification over all models in Keisler's order, [Definition 3.10](#) below.

Theorem B. (Keisler [8, Corollary 2.1, p. 30]; see also Shelah [20, VI.1].) Suppose that $M_0 \equiv M_1$, the ambient language is countable, and \mathcal{D} is a regular ultrafilter on λ . Then $M_0^\lambda / \mathcal{D}$ is λ^+ -saturated iff $M_1^\lambda / \mathcal{D}$ is λ^+ -saturated.

Fact 3.4. Any nonprincipal ultrapower in a countable language is \aleph_1 -saturated.

The connection of the following definition to saturation was sketched in the introduction.

Definition 3.5. A function with domain $\mathcal{P}_{\aleph_0}(\kappa)$ is called *monotonic* if $u \subseteq v \in \mathcal{P}_{\aleph_0}(\kappa)$ implies $f(v) \subseteq f(u)$, and *multiplicative* if $f(u) \cap f(v) = f(u \cup v)$. We say that g is a *refinement* of f if $g(u) \subseteq f(u)$ for all $u \in \mathcal{P}_{\aleph_0}(\kappa)$.

Consider [Definition 3.5](#) through the lens of the following example: $u = \{\varphi(x, a)\}$, $v = \{\psi(x, b)\}$, $f(u) \subseteq \{t < \lambda : M \models \exists x \varphi(x, a[t])\}$, $f(v) \subseteq \{t < \lambda : M \models \exists x \varphi(x, b[t])\}$, and $f(u \cup v) \subseteq \{t < \lambda : M \models \exists x (\varphi(x, a[t]) \wedge \varphi(x, b[t]))\}$. Then monotonicity is the natural requirement that $f(u \cup v) \subseteq f(v) \cap f(u)$, and multiplicativity asks that equality holds, meaning that on the indices we've chosen, whenever φ and ψ each have a realization, then they have a common realization.

From the point of view of saturation, the most powerful ultrafilters are the *good* ultrafilters, introduced by Keisler [7]. These saturate any [countable] theory, and thus witness the existence of a maximum class in Keisler's order.

Definition 3.6. A filter \mathcal{D} on $\lambda \geq \aleph_0$ is called κ^+ -good if every monotonic function $f : \mathcal{P}_{\aleph_0}(\kappa) \rightarrow \mathcal{D}$ has a multiplicative refinement. \mathcal{D} is called *good* if it is λ^+ -good.

Keisler proved the existence of λ^+ -good countably incomplete ultrafilters on λ assuming $2^\lambda = \lambda^+$. Kunen [9] gave a proof in ZFC, using independent families of functions (also called families of large oscillation). Kunen's construction technique and its subsequent development by the second author in Chapter VI of [20] is a key ingredient of our approach in this paper.

We now give some important model-theoretic properties. The reader interested primarily in ultrafilters rather than model theory may take these properties as black boxes which give the non-saturation side of the argument in [Section 9](#).

Definition 3.7 (*Simple, low*). Given a background theory T ,

- (1) A formula $\varphi = \varphi(x, y)$ has the k -tree property, for $k < \omega$, when there exist parameters $\{a_\eta: \eta \in {}^{\omega>} \omega\}$, $\ell(a_\eta) = \ell(y)$, so that:
 - (a) for each $\eta \in {}^{\omega>} \omega$, the set $\{\varphi(x, a_{\eta \smallfrown i}): i < \omega\}$ is k -inconsistent, and
 - (b) for each $\eta \in {}^\omega \omega$, the set $\{\varphi(x, a_{\eta \smallfrown n}): n < \omega\}$ is a consistent partial type.
- (2) A formula φ is *simple* if it does not have the tree property, i.e. it does not have the k -tree property for any k .
- (3) A formula $\varphi = \varphi(x, y)$ is *low* if there is $k = k_\varphi$ so that for any indiscernible sequence of parameters $\langle a_i: i < \omega \rangle$, $\ell(a_i) = \ell(y)$, if $\{\varphi(x; a_i): i < \omega\}$ is 1-consistent, i.e. each 1-element subset is consistent, then either it is consistent or it is uniformly k -inconsistent, i.e. each k -element subset is inconsistent.
- (4) T is said to be *simple*, respectively *low*, if every formula of T is.
- (5) A theory which is not low is often called *non-low*.

Remark 3.8. [Definition 3.7](#) may also be formulated in terms of Shelah's D-rank: a formula is simple if for every $k < \omega$, $D(x = x, \{\varphi\}, k) < \omega$ and is low if there exists $k = k_\varphi < \omega$ so that $D(x = x, \{\varphi\}, \infty) = D(x = x, \{\varphi\}, k)$. For simple theories, this second is equivalent to Buechler's original definition [1] which asked that for every φ , $D(x = x, \{\varphi\}, \aleph_0) < \omega$.

Discussion 3.9 (*On simple, non-low theories*). On one hand, there are many theories which are simple and low: for instance, all stable theories, the random graph, and the model companion ACFA of the theory of difference fields. On the other, there are also theories which are simple and non-low. The basic example is the model completion of the following. Consider a two-sorted structure with an infinite set on one side, an equivalence relation with infinitely many infinite classes on the other, and an edge relation R connecting the two, with axioms saying that an element on the left is connected to precisely n elements of the n th equivalence class on the right. See Casanovas and Kim [2] for an example of a supersimple non-low theory.

Finally, we define Keisler's order, proposed in Keisler 1967 [8]. This preorder \trianglelefteq on theories is often thought of as a partial order on the \trianglelefteq -equivalence classes. The hypothesis *regular*, [Definition 3.3](#), justifies the quantification over all models.

Definition 3.10. (See Keisler [8].) Given countable theories T_1, T_2 , say that:

- (1) $T_1 \trianglelefteq_\lambda T_2$ if for any $M_1 \models T_1$, $M_2 \models T_2$, and \mathcal{D} a regular ultrafilter on λ , if $M_2^\lambda / \mathcal{D}$ is λ^+ -saturated then $M_1^\lambda / \mathcal{D}$ must be λ^+ -saturated.
- (2) (*Keisler's order*) $T_1 \trianglelefteq T_2$ if for all infinite λ , $T_1 \trianglelefteq_\lambda T_2$.

Informally, for all regular \mathcal{D} , \mathcal{D} saturates T_2 implies that \mathcal{D} saturates T_1 .

Project 3.11. Determine the structure of Keisler's order.

4. Excellent filters

In this section we define “ λ^+ -excellent filter”, [Definition 4.6](#) below and develop some consequences of this definition.

Convention 4.1 (*Conventions*).

- We consider Boolean algebras in the language $\{\cap, \cup, \leq, -, 0, 1\}$ and will informally use symmetric difference Δ and setminus \setminus . (Note that negation of \mathbf{a} will be denoted $1 - \mathbf{a}$; overline, e.g. $\bar{\mathbf{a}}$, always denotes a sequence, not the complement of a set.)
- \mathfrak{B} denotes a Boolean algebra, and all elements of Boolean algebras are written in boldface: $\mathbf{a}, \mathbf{b}, \dots$.
- $CC(\mathfrak{B})$ (“chain condition”) is the minimum regular cardinal μ so that any partition (maximal disjoint subset) of \mathfrak{B} has cardinality less than μ .
- For \mathcal{D} a filter on the index set I , $B(\mathcal{D})$ is the Boolean algebra $\mathcal{P}(I)/\mathcal{D}$.
- When \mathcal{D} is a filter on an index set I (or a Boolean algebra \mathfrak{B}), \mathcal{D}^+ denotes the sets which are positive modulo \mathcal{D} , i.e. not equal to $\emptyset \bmod \mathcal{D}$.
- If X is a formula then we use the shorthand X^1, X^0 to denote $X, \neg X$ respectively.
- Δ is used both for symmetric difference and for sets of formulas, but this is always clear from the context.
- \mathcal{D}, \mathcal{E} denote filters.

Definition 4.2 (*Boolean terms*).

- (1) Let u be a finite set. We write $\bar{x}_{\mathcal{P}(u)} = \langle x_v : v \subseteq u \rangle$ for a sequence of variables indexed by subsets of u .
- (2) By a *Boolean term* we mean a term in the language of Boolean algebras, see [Convention 4.1](#).
- (3) For a Boolean term σ , we write $\sigma = \sigma(\bar{x}_{\mathcal{P}(u)})$ to indicate that the free variables are indexed this way. For $\sigma = \sigma(\bar{x}_{\mathcal{P}(u)})$ a Boolean term and $\langle A_u : u \in [\lambda]^{<\aleph_0}$ a sequence of elements of some given Boolean algebra, we write $\sigma(\bar{A}|_{\mathcal{P}(u)})$ or equivalently, $\sigma(\langle A_v : v \subseteq u \rangle)$ for the term evaluated on the relevant part of the sequence.

We will consider certain distinguished sets of Boolean terms. For further motivation, see [Example 4.8](#) and [Claim 4.9](#) below.

Definition 4.3. Let \mathfrak{B} be a Boolean algebra and $\bar{\mathbf{a}} = \langle \mathbf{a}_u : u \in [\lambda]^{<\aleph_0} \rangle$ be a sequence of elements of \mathfrak{B} . Define the set “below $\bar{\mathbf{a}}$ ” as

$$N(\bar{\mathbf{a}}|_{\mathcal{P}(u)}) = \{ \langle \mathbf{a}'_v : v \subseteq u \rangle : \text{for some } w \subseteq u \text{ we have } \mathbf{a}'_v = \mathbf{a}_v \text{ if } v \subseteq w \text{ and } \mathbf{a}'_v = 0_{\mathfrak{B}} \text{ otherwise} \}.$$

Remark 4.4. For the purposes of this paper, we are interested in so-called possibility patterns, [Definition 6.1](#) and thus it will be sufficient to restrict to *monotonic*, $[\lambda]^{<\aleph_0}$ -indexed sequences, i.e. $v \subseteq u \implies \mathbf{a}_u \subseteq \mathbf{a}_v$, allowing some elements of the sequence to be 0.

Definition 4.5. For \mathfrak{B} a Boolean algebra, u finite, $\bar{a} = \langle a_v : v \subseteq u \rangle$ a sequence of members of \mathfrak{B} ,

- (1) Define $A_{\mathfrak{B}, \bar{a}}$ to be the set

$$\{ \sigma(\bar{x}_{\mathcal{P}(u)}) : \sigma(\bar{x}_{\mathcal{P}(u)}) \text{ is a Boolean term so that } \mathfrak{B} \models “\sigma(\bar{a}') = 0” \text{ whenever } \bar{a}' \in N(\bar{a}) \}.$$

- (2) If \mathcal{D} is a filter on \mathfrak{B} then $\Lambda_{\mathfrak{B}, \mathcal{D}, \bar{a}} = \Lambda_{\mathfrak{B}_1, \bar{a}_1}$ where $\mathfrak{B}_1 = \mathfrak{B}/\mathcal{D}$ and $\bar{a}_1 = \langle a_v/\mathcal{D}: v \subseteq u \rangle$.
- (3) If \mathcal{D} is a filter on a set I , then \mathcal{D} determines I , so we write $\Lambda_{\mathcal{D}, \bar{a}}$ for $\Lambda_{\mathcal{P}(I), \mathcal{D}, \bar{a}}$.

We now give one of the central definitions of the paper:

Definition 4.6 (*Excellent filters*). Let \mathcal{D} be a filter on the index set I . We say that \mathcal{D} is λ^+ -*excellent* when: if $\bar{A} = \langle A_u: u \in [\lambda]^{<\aleph_0} \rangle$ with $u \in [\lambda]^{<\aleph_0} \implies A_u \subseteq I$, then we can find $\bar{B} = \langle B_u: u \in [\lambda]^{<\aleph_0} \rangle$ so that:

- (1) for each $u \in [\lambda]^{<\aleph_0}$, $B_u \subseteq A_u$,
- (2) for each $u \in [\lambda]^{<\aleph_0}$, $B_u = A_u \bmod \mathcal{D}$,
- (3) if $u \in [\lambda]^{<\aleph_0}$ and $\sigma \in \Lambda_{\mathcal{D}, \bar{A}|_u}$, so $\sigma(\bar{A}|_{\mathcal{P}(u)}) = \emptyset \bmod \mathcal{D}$, then $\sigma(\bar{B}|_{\mathcal{P}(u)}) = \emptyset$.

We say that \mathcal{D} is ξ -*excellent* when it is λ^+ -*excellent* for every $\lambda < \xi$.

In this paper we focus on regular excellent filters. Since we will often refer to sequences of the kind just described, we give them a name:

Definition 4.7. Given I , \mathcal{D} , \bar{A} as in [Definition 4.6](#), we will call any \bar{B} satisfying (1)–(3) of [Definition 4.6](#) a \mathcal{D} -*excellent refinement* of \bar{A} . When \mathcal{D} is clear from the context, we may simply say “*excellent refinement*”.

Example 4.8. Essentially, the distinguished terms capture equations we can solve by isolating zero-sets which we can safely eliminate. As an example of why respecting *all* Boolean terms would be too strong (that is, why it would be too strong to ask that all terms which evaluate to 0 mod \mathcal{D} on \bar{A} would evaluate to 0 on \bar{B}), consider a monotonic sequence $\bar{A} = \langle A_u: u \in [\lambda]^{<\aleph_0} \rangle$ of elements of \mathcal{D} . Then for each $u, v \in [\lambda]^{<\aleph_0}$, $A_u = A_v \bmod \mathcal{D}$, i.e. $A_u \Delta A_v = \emptyset \bmod \mathcal{D}$. Asking for a \mathcal{D} -equivalent refinement \bar{B} in which $u, v \in [\lambda]^{<\aleph_0}$ implies $B_u = B_v$ would require an instance of completeness, i.e. $\bigcap \{A_u: u \in [\lambda]^{<\aleph_0}\} \in \mathcal{D}$.

We now verify that the cases of main interest are captured by the definition of excellent.

Claim 4.9. Let \mathcal{D} be a filter on I , i.e. on $\mathcal{P}(I)$.

- (1) If \mathcal{D} is λ^+ -*excellent* and $A_u \subseteq I$ for $u \in [\lambda]^{<\aleph_0}$, then we can find \bar{B} so that:
 - (a) $\bar{B} = \langle B_u: u \in [\lambda]^{<\aleph_0} \rangle$,
 - (b) $B_u \subseteq A_u$,
 - (c) $B_u = A_u \bmod \mathcal{D}$,
 - (d) for all $u_0, u_1 \in [\lambda]^{<\aleph_0}$, if $A_{u_0} \cap A_{u_1} = A_{u_0 \cup u_1} \bmod \mathcal{D}$ then $B_{u_0} \cap B_{u_1} = B_{u_0 \cup u_1}$.
- (2) If \mathcal{D} is λ^+ -*excellent* and $A_\alpha \subseteq I$ for $\alpha < \lambda$, then we can find \bar{B} so that:
 - (a) $\bar{B} = \langle B_\alpha: \alpha < \lambda \rangle$,
 - (b) $B_\alpha \subseteq A_\alpha$,
 - (c) $B_\alpha = A_\alpha \bmod \mathcal{D}$,
 - (d) if $n \in \mathbb{N}$, $\alpha_0, \dots, \alpha_{n-1} < \lambda$ and $\bigcap \{A_{\alpha_\ell}: \ell < n\} = \emptyset \bmod \mathcal{D}$, then $\bigcap \{B_{\alpha_\ell}: \ell < n\} = \emptyset$.
- (3) If \mathcal{D} is λ^+ -*excellent* then \mathcal{D} is λ^+ -*good*.

Proof. Note that (3) follows from (1) in the case where the sequence $\langle A_u: u \in [\lambda]^{<\aleph_0}$ is assumed to be a monotonic sequence of elements of \mathcal{D} .

(1) Let $\bar{A} = \langle A_u: u \in [\lambda]^{<\aleph_0}$ be given, with $A_u \in \mathcal{D}^+$ (otherwise replace A_u by \emptyset). We are assuming \mathcal{D} is λ^+ -excellent, so let $\bar{B} = \langle B_u: u \in [\lambda]^{<\aleph_0}$ be an excellent refinement. Then conditions (a), (b), (c) hold by definition. For condition (d), it will suffice to show that if for all $u_0, u_1 \in [\lambda]^{<\aleph_0}$, $(*) A_{u_0} \cap A_{u_1} = A_{u_0 \cup u_1} \text{ mod } \mathcal{D}$, then $(**)$, where $(**)$ is the condition that, writing $u = u_0 \cup u_1$, the Boolean term

$$\sigma(\bar{x}_{\mathcal{P}(u)}) = ((x_{u_0} \cap x_{u_1}) \Delta x_u) \text{ belongs to } \Lambda_{\mathcal{D}, \bar{A}|_{\mathcal{P}(u)}}.$$

Why would this suffice? Because we would then have, as an immediate consequence of “excellent refinement”, that $u_0, u_1 \in [\lambda]^{<\aleph_0}$ implies $B_{u_0} \cap B_{u_1} = B_u$ since $(**)$ implies $A_{u_0} \cap A_{u_1} = A_u \text{ mod } \mathcal{D}$.

So let us prove that $(*)$ implies $(**)$. That is, we verify that $(*)$ implies σ evaluates to $\emptyset \text{ mod } \mathcal{D}$ on any term “below” $\bar{A}|_{\mathcal{P}(u)}$ in the sense of [Definition 4.3](#). For any $w \subseteq u := u_0 \cup u_1$,

- if $w = u$, then $\sigma = \emptyset \text{ mod } \mathcal{D}$ as $A_{u_0} \cap A_{u_1} = A_u \text{ mod } \mathcal{D}$ by $(*)$;
- if $w \subseteq u_1 \wedge w \not\subseteq u_0$ then we have either $\emptyset \cap \emptyset = \emptyset \text{ mod } \mathcal{D}$ or else $A_{u_0} \cap \emptyset = \emptyset \text{ mod } \mathcal{D}$, both of which are clearly true;
- the case $w \not\subseteq u_1 \wedge w \subseteq u_0$ is the same as the previous case by symmetry.

In other words, since a sufficient condition for being multiplicative is expressible by one of our distinguished terms, any sequence \bar{A} which is multiplicative $\text{mod } \mathcal{D}$, even if it does not itself consist of elements of \mathcal{D} , will have a true multiplicative refinement \bar{B} as desired.

This completes the proof.

(2) We may naturally extend \bar{A} to a monotonic sequence of elements of $\mathcal{P}(I)$ indexed by $u \in [\lambda]^{<\aleph_0}$, where $|u| \geq 2 \implies A_u = \emptyset$. Let $\langle A'_u: u \in [\lambda]^{<\aleph_0}$ be such a sequence, writing $A_\alpha = A_{\{\alpha\}}$. Apply [Definition 4.6](#) to obtain an excellent refinement $\langle B'_u: u \in [\lambda]^{<\aleph_0}$. Let $B_\alpha = B'_{\{\alpha\}}$. Conditions (a)–(c) clearly hold. For condition (d), let $n \in \mathbb{N}$, $a_0, \dots, a_{n-1} < \lambda$, $u = \{a_0, \dots, a_{n-1}\}$; it suffices to check that the Boolean term

$$\sigma(x_{\{a_0\}}, \dots, x_{\{a_{n-1}\}}) = x_{\{a_0\}} \cap \dots \cap x_{\{a_{n-1}\}} \in \Lambda_{\mathcal{D}, u}.$$

If $w = u$, the demand is that $A'_{\{a_0\}} \cap \dots \cap A'_{\{a_{n-1}\}} = \emptyset \text{ mod } \mathcal{D}$, which holds by hypothesis. If $w \subsetneq u$ then in the intersection we replace at least one $A_{\{\alpha\}}$ by \emptyset , so the intersection is empty as desired. \square

Remark 4.10. [Claim 4.9](#) remains true in the case where we replace $\mathcal{P}(I)$ by an arbitrary Boolean algebra \mathfrak{B} , with the same proof.

5. Excellence and goodness

In this section we investigate the relationship between excellence and goodness and prove a characterization in the base case (this remark is explained by [Discussion 5.3](#)). The characterization is [Theorem 5.2](#).

Claim 5.1. *Assume \mathcal{D} is a filter on the Boolean algebra \mathfrak{B} . If \mathcal{D} is λ^+ -good then \mathcal{D} is λ^+ -excellent.*

Proof. Let $\bar{\mathbf{a}} = \langle \mathbf{a}_u : u \in [\lambda]^{<\aleph_0} \rangle$ be a sequence of elements of \mathfrak{B} , and we look for an excellent refinement. That is, let $\Lambda = \Lambda_{\mathfrak{B}, \mathcal{D}, \bar{\mathbf{a}}}$ as in Definition 4.5 above, and $\mathfrak{B}_1 = \mathfrak{B}/\mathcal{D}$. Then we would like to find $\langle \mathbf{b}_u : u \in [\lambda]^{<\aleph_0} \rangle$ so that whenever $\sigma = \sigma(\bar{x}_{\mathcal{P}(u)}) \in \Lambda$, i.e. $\sigma(\bar{\mathbf{a}}') = 0_{\mathfrak{B}_1}$ for any $\bar{\mathbf{a}}'$ below $\bar{\mathbf{a}}$ in the sense of Definition 4.3 (for the Boolean algebra \mathfrak{B}_1), we have that $\sigma(\bar{\mathbf{b}}) = 0_{\mathfrak{B}}$.

Step 1: Safe sets. First, for each $u \in [\lambda]^{<\aleph_0}$ define

$$\mathbf{a}_u^1 = \bigcap \{ 1_{\mathfrak{B}} - \sigma(\bar{\mathbf{a}} \upharpoonright_{\mathcal{P}(\zeta)}) : \zeta \subseteq u, \sigma(\bar{x}_{\mathcal{P}(\zeta)}) \in \Lambda \}.$$

By construction, $\bar{\mathbf{a}}^1 = \langle \mathbf{a}_u^1 : u \in [\lambda]^{<\aleph_0} \rangle$ is a monotonic sequence of elements of \mathcal{D} .

Step 2: A multiplicative refinement. Apply the hypothesis of goodness to obtain a multiplicative refinement $\bar{\mathbf{b}}^1 = \langle \mathbf{b}_u^1 : u \in [\lambda]^{<\aleph_0} \rangle$ of $\bar{\mathbf{a}}^1$. Each \mathbf{b}_u^1 is an element of \mathfrak{B} , in fact of \mathcal{D} .

Step 3: The sequence $\bar{\mathbf{b}}$. Define $\bar{\mathbf{b}} = \langle \mathbf{b}_u : u \in [\lambda]^{<\aleph_0} \rangle$ where $\mathbf{b}_u = \mathbf{a}_u \cap \mathbf{b}_u^1$ for each $u \in [\lambda]^{<\aleph_0}$. In the remainder of the proof, we show that $\bar{\mathbf{b}}$ is the desired excellent refinement of $\bar{\mathbf{a}}$. We have immediately from the definition that for each $u \in [\lambda]^{<\aleph_0}$,

- (a) $\mathbf{b}_u \in \mathfrak{B}$,
- (b) $\mathfrak{B} \models \mathbf{b}_u \leq \mathbf{a}_u$,
- (c) $\mathbf{b}_u = \mathbf{a}_u \bmod \mathcal{D}$.

It remains to show that excellence holds.

Step 4: Excellence of $\bar{\mathbf{b}}$. For this step, we consider $u \in [\lambda]^{<\aleph_0}$ and $\sigma = \sigma(\bar{x}_{\mathcal{P}(u)}) \in \Lambda = \Lambda_{\mathfrak{B}, \mathcal{D}, \bar{\mathbf{a}}}$.

4a: *Remarks.* First, by definition of Λ and the fact that 0 is a constant of the language of Boolean algebras, whenever $\sigma = \sigma(\bar{x}_{\mathcal{P}(u)}) \in \Lambda = \Lambda_{\mathfrak{B}, \mathcal{D}, \bar{\mathbf{a}}}$ and $\bar{\mathbf{a}}'$ is below $\bar{\mathbf{a}} \upharpoonright_{\mathcal{P}(u)}$ with respect to \mathfrak{B} [note: this means substituting in $0_{\mathfrak{B}}$, not $0_{\mathfrak{B}_1}$, for some elements of $\bar{\mathbf{a}}'$] we have that $\mathbf{a}_u^1 \subseteq 1 - \sigma(\bar{\mathbf{a}}')$.

Second, if $\zeta \subseteq u$ and $\bar{\mathbf{a}}'$ is below $\bar{\mathbf{a}} \upharpoonright_{\mathcal{P}(u)}$ in the sense that $\mathbf{a}'_w = \mathbf{a}_w$ if $w \subseteq \zeta$ and $\mathbf{a}'_w = 0_{\mathfrak{B}}$ otherwise, then $\mathbf{a}'_{\zeta} \subseteq 1 - \sigma(\bar{\mathbf{a}}')$, just by applying the previous remark twice.

4b: *A partition.* For each $u \in [\lambda]^{<\aleph_0}$ and $\zeta \subseteq u$, define

$$\mathbf{c}_{\zeta, u} = \mathbf{b}_{\zeta}^1 \setminus \bigcup \{ \mathbf{b}_{\zeta \cup \{t\}}^1 : t \in u \setminus \zeta \} = \bigcap \{ \mathbf{b}_t^1 : t \in \zeta \} \setminus \bigcup \{ \mathbf{b}_t^1 : t \in u \setminus \zeta \}$$

where the second equality uses multiplicativity of $\bar{\mathbf{b}}^1$. Thus $\{ \mathbf{c}_{\zeta, u} : \zeta \subseteq u \}$ gives a partition of \mathbf{b}_u^1 , thus also of $\mathbf{b}_u \leq \mathbf{b}_u^1$. It will suffice to show that if $\zeta \subseteq u$ and $\mathbf{c} = \mathbf{c}_{\zeta, u} > 0$ or $\mathbf{c} = 1 - \mathbf{b}_{\emptyset}^1$, then $\mathfrak{B} \upharpoonright_{\mathbf{c}_{\zeta, u}} \models \sigma(\dots, \mathbf{b}_w \cap \mathbf{c}, \dots)_{w \subseteq u} = 0$.

4c: *Cases.* First, we may justify restricting to \mathbf{b}_{\emptyset}^1 as $\sigma(\dots, 0, \dots) = 0$.

Then letting ζ vary, we use $\{ \mathbf{c}_{\zeta, u} : \zeta \subseteq u \}$ to partition \mathbf{b}_{\emptyset}^1 . It suffices to show that for each $\mathbf{c}_{\zeta, u}$, $\mathfrak{B} \upharpoonright_{\mathbf{c}_{\zeta, u}} \models \sigma(\bar{\mathbf{b}} \upharpoonright_{\mathcal{P}(u)}) = 0$. Let $u \in [\lambda]^{<\aleph_0}$ and $\zeta \subseteq u$ be given.

If $w \subseteq \zeta$, then $\mathbf{c}_{\zeta, u} \leq \mathbf{b}_w^1 \leq \mathbf{b}_w^1$ by definition and by monotonicity. Hence $\mathbf{b}_w \cap \mathbf{b}_w^1 \cap \mathbf{c}_{\zeta, u} = \mathbf{b}_w \cap \mathbf{c}_{\zeta, u} = \mathbf{a}_w \cap \mathbf{b}_w^1 \cap \mathbf{c}_{\zeta, u} = \mathbf{a}_w \cap \mathbf{c}_{\zeta, u}$, i.e. on $\mathbf{c}_{\zeta, u}$ we have that $\mathbf{b}_w = \mathbf{a}_w$.

If $w \subseteq u \wedge w \not\subseteq \zeta$ then $\mathbf{b}_w^1 \cap \mathbf{c}_{\zeta, u} = 0_{\mathfrak{B}}$ by definition of $\mathbf{c}_{\zeta, u}$, and $\mathbf{b}_w \leq \mathbf{b}_w^1$, thus $\mathbf{b}_w \cap \mathbf{c}_{\zeta, u} = 0$.

In other words, writing

- $\mathbf{b}_w^* = \mathbf{b}_w$ if $\zeta \subseteq w$ and $0_{\mathfrak{B}}$ otherwise, and
- $\mathbf{b}_w^c = \mathbf{b}_w \cap \mathbf{c}_{\zeta,u}$ if $\zeta \subseteq w$ and $0_{\mathfrak{B}}$ otherwise,

we have shown that

$$(\mathfrak{B} \upharpoonright_{\mathbf{c}_{\zeta,u}} \models \sigma(\dots \mathbf{b}_w^c \dots)_{w \subseteq u} = 0) \iff (\mathfrak{B} \models \sigma(\dots \mathbf{b}_w^* \dots)_{w \subseteq u} \cap \mathbf{c}_{\zeta,u} = 0).$$

Now by definition of $\mathbf{c}_{\zeta,u}$, the monotonicity of $\bar{\mathbf{b}}^1$, and Step 4a, we have that

$$\mathbf{c}_{\zeta,u} \subseteq \bigcap \{ \mathbf{b}_{\{i\}}^1 : i \in \zeta \} \subseteq \mathbf{b}_{\zeta}^1 \subseteq \mathbf{a}_{\zeta}^1 \subseteq 1 - \sigma(\dots \mathbf{b}_w^* \dots)_{w \subseteq u}$$

which completes the proof. \square

Theorem 5.2 (A new characterization of goodness). *Let \mathcal{D} be a filter on the Boolean algebra \mathfrak{B} . Then the following are equivalent.*

- (1) \mathcal{D} is λ^+ -good.
- (2) \mathcal{D} is λ^+ -excellent.

Proof. (1) \rightarrow (2) [Claim 4.9](#), via [Remark 4.10](#).

(2) \rightarrow (1) [Claim 5.1](#). \square

Discussion 5.3. One can naturally localize excellence and goodness to formulas (so that the configurations we try to refine are those arising from distributions or weak distributions of φ -types) or to theories. From this point of view, [Theorem 5.2](#) shows that equivalence holds in the base case: \mathcal{D} is good for all formulas in all theories iff \mathcal{D} is excellent for all formulas in all theories. Otherwise, for strictly smaller classes, the situation appears to be different. For instance, in work in progress, the authors are investigating the connection of goodness to atomic saturation versus the connection of excellence to quantifier-free saturation, and we have shown that locally, excellence and goodness can be distinguished. We believe it will be very interesting to find the future points of contact and divergence of these two major properties as one varies the formulas or theories under consideration.

6. Separation of variables

The main result of the section is “separation of variables”, [Theorem 6.13](#). The reader may find it useful to refer to the discussion in [Section 2](#) above, which frames this result.

Definition 6.1 (Possibility patterns). Let \mathfrak{B} be a Boolean algebra. Say that $\bar{\mathbf{a}}$ is a $(\lambda, \mathfrak{B}, T, \varphi)$ -possibility when:

- (1) $\bar{\mathbf{a}} = \langle \mathbf{a}_u : u \in [\lambda]^{<\aleph_0} \rangle$,
- (2) $u \in [\lambda]^{<\aleph_0}$ implies $\mathbf{a}_u \in \mathfrak{B}^+$,
- (3) if $v \subseteq u \in [\lambda]^{<\aleph_0}$ then $\mathbf{a}_u \subseteq \mathbf{a}_v$ (monotonicity),
- (4) if $u_* \in [\lambda]^{<\aleph_0}$ and $\mathbf{b} \in \mathfrak{B}^+$ satisfies

$$(u \subseteq u_* \implies ((\mathbf{b} \leq \mathbf{a}_u) \vee (\mathbf{b} \leq 1 - \mathbf{a}_u))) \wedge (\alpha \in u_* \implies \mathbf{b} \leq \mathbf{a}_{\{\alpha\}})$$

then we can find a model $M \models T$ and $a_\alpha \in M$ for $\alpha \in u_*$ so that for every $u \subseteq u_*$,

$$M \models (\exists x) \bigwedge_{\alpha \in u} \varphi(x; a_\alpha) \quad \text{iff} \quad \mathbf{b} \leq \mathbf{a}_u.$$

Discussion 6.2. As regards [Definition 6.1](#):

- (1) The requirement that $\mathbf{b} \leq \mathbf{a}_{\{\alpha\}}$ reflects the fact that, informally speaking, we are interested in looking at a sequence of sets representing instances of a formula φ (for instance, sets contained in the \mathbf{j} -image of the Łoś map of $\varphi(x, b_\alpha)$) and we would like them to be accurate in the sense that any ultrafilter induced on these sets by a nonzero element \mathbf{b} reflects a pattern of consistency and inconsistency which is possible to achieve using this given formula, in some model, with some sequence of parameters – thus the name “possibility pattern”.
- (2) In order to build ultrafilters on Boolean algebras which saturate a given theory, we will need a way to capture those sequences whose multiplicative refinements are truly necessary for, or visible to, the theory in question. A slogan for [Definition 6.1](#) might be that “any nonzero element of \mathfrak{B} inducing an ultrafilter on $\bar{\mathbf{a}}$ reveals a consistent φ -configuration”, e.g. in the sense of the characteristic sequences of [\[12\]](#).

Definition 6.3 (*Moral ultrafilters on Boolean algebras*). We say that an ultrafilter \mathcal{D} on the Boolean algebra \mathfrak{B} is $(\lambda, \mathfrak{B}, T, \varphi)$ -moral when for every $(\lambda, \mathfrak{B}, T, \varphi)$ -possibility $\bar{\mathbf{a}} = \langle \mathbf{a}_u : u \in [\lambda]^{<\aleph_0} \rangle$ satisfying

- $u \in [\lambda]^{<\aleph_0} \implies \mathbf{a}_u \in \mathcal{D}$,
- (by definition of possibility) $v \subseteq u \in [\lambda]^{<\aleph_0} \implies \mathbf{a}_u \subseteq \mathbf{a}_v$

there is a multiplicative \mathcal{D} -refinement $\bar{\mathbf{b}} = \langle \mathbf{b}_u : u \in [\lambda]^{<\aleph_0} \rangle$, i.e.

- (1) $u_1, u_2 \in [\lambda]^{<\aleph_0} \implies \mathbf{b}_{u_1} \cap \mathbf{b}_{u_2} = \mathbf{b}_{u_1 \cup u_2}$,
- (2) $u \in [\lambda]^{<\aleph_0} \implies \mathbf{b}_u \subseteq \mathbf{a}_u$,
- (3) $u \in [\lambda]^{<\aleph_0} \implies \mathbf{b}_u \in \mathcal{D}$.

We write $(\lambda, \mathfrak{B}, T, \Delta)$ -moral to mean $(\lambda, \mathfrak{B}, T, \varphi)$ -moral for all $\varphi \in \Delta$, and $(\lambda, \mathfrak{B}, T)$ -moral to mean for all formulas φ in the language of T , see [Remark 6.4](#).

Remark 6.4. Note that “ $(\lambda, \mathfrak{B}, T)$ -moral” in [Definition 6.3](#) indeed means that morality holds locally, for each φ . The global and local cases are not different in our context thanks to [Fact 6.6](#), or, in the case of a larger language, [Corollary 6.7](#).

Definition 6.5. Let φ be a formula in the language of T . A “ φ -type” over a given parameter set is a consistent set of positive and negative instances of φ with parameters from that set.

Fact 6.6 (*Local saturation implies saturation, [11, Theorem 12]*). Suppose \mathcal{D} is a regular ultrafilter on I and T a countable complete first-order theory. Then for any M^I/\mathcal{D} , the following are equivalent:

- (1) M^I/\mathcal{D} is λ^+ -saturated.
- (2) M^I/\mathcal{D} realizes all φ -types over sets of size $\leq \lambda$, for all formulas φ in the language of T .

In this paper, we focus on countable theories for transparency, but many of the results we use and prove, including [Fact 6.6](#), may be extended to a more general context.²

Definition 6.8 (*Distributions*). Let T be a countable complete first-order theory, $M \models T$, \mathcal{D} a regular ultrafilter on I , $|I| = \lambda$, $N = M^\lambda / \mathcal{D}$. Let $p(x) = \{\varphi_\alpha(x; a_\alpha) : \alpha < \lambda\}$ be a consistent partial type in N . Then a *distribution* of p is a map $d : \mathcal{P}_{\aleph_0}(\lambda) \rightarrow \mathcal{P}(I)$ which satisfies:

- (1) $\text{Range}(d) \subseteq \mathcal{D}$,
- (2) for each $u \in [\lambda]^{<\aleph_0}$, $d(u) \subseteq \{t \in I : M \models \exists x \bigwedge \{\varphi_\alpha(x; a_\alpha[t]) : \alpha \in u\}\}$. Informally speaking, d refines the Łoś map,
- (3) d is monotonic,
- (4) for each $t \in I$, $|\{u \in \mathcal{P}(I) : t \in d(u)\}| < \aleph_0$. Note that in the presence of (1), this implies the range of d is a regularizing family.

A map satisfying (2), (3), (4) is called a *weak distribution*. A distribution satisfying the additional conditions of [Observation 6.11](#) is called *accurate*.

Convention 6.9. We will often identify a distribution or weak distribution d with the image of $[\lambda]^{<\aleph_0}$ under d , i.e. with a sequence of the form $\langle A_u : u \in [\lambda]^{<\aleph_0} \rangle \subseteq \mathcal{P}(I)$.

Observation 6.10. (See e.g. [\[15, Observation 1.8\]](#).) Let T be a countable complete first-order theory, $M \models T$, \mathcal{D} a regular ultrafilter on λ , $N = M^\lambda / \mathcal{D}$. Then the following are equivalent:

- (1) For every consistent partial type p in N of size $\leq \lambda$, some distribution d of p has a multiplicative refinement.
- (2) N is λ^+ -saturated.

Observation 6.11. Let M, N, T, I, p be as in [Definition 6.8](#). If p has a (weak) distribution, we may choose a (weak) distribution d of p which is accurate, where this means that in addition: for each $t \in I$ and $u \subseteq \{\alpha < \lambda : t \in d(\{\alpha\})\}$,

$$M \models \exists x \bigwedge \{\varphi_\alpha(x; a_\alpha[t]) : \alpha \in u\} \iff t \in d(u).$$

Proof. Let $p = \{\varphi_\alpha(x, a_\alpha) : \alpha < \lambda\}$. Let $d_0 : \lambda \rightarrow \mathcal{D}$ be given by the Łoś map, that is,

$$\alpha \mapsto \{t < \lambda : M \models \exists x \varphi_\alpha(x, a_\alpha[t])\}.$$

² The argument of [\[11, §3\]](#) extends to larger languages; the only change is the limit stages, which follow from the stronger hypothesis that $\text{lcf}(|T|, \mathcal{D}) \geq \lambda^+$. The full statement is:

Corollary 6.7. Let T be a complete first-order theory. Suppose \mathcal{D} is a regular ultrafilter on I which is $|T|^+$ -good, or just so that $\text{lcf}(|T|, \mathcal{D}) \geq \lambda^+$. Then for any M^I / \mathcal{D} , the following are equivalent:

- (1) M^I / \mathcal{D} is λ^+ -saturated.
- (2) M^I / \mathcal{D} realizes all φ -types over sets of size $\leq \lambda$, for all formulas φ in the language of T .

Let $\{X_\alpha: \alpha < \lambda\}$ be a regularizing family for \mathcal{D} . Let $d_1: [\lambda]^1 \rightarrow \mathcal{D}$ be given by: $\{\alpha\} \mapsto d_0(\alpha) \cap X_\alpha$. Now for each $t < \lambda$, the set $\{\alpha < \lambda: t \in d_1(\{\alpha\})\}$ is finite. Finally, define $d: [\lambda]^{<\aleph_0} \rightarrow \mathcal{D}$ as follows. On sets of size 1, $d = d_0$. For each $n > 1$ and $u \in [\lambda]^n$, define

$$d(u) = \left\{ t < \lambda: (\forall \alpha \in u) (t \in d(\{\alpha\})) \wedge M \models \exists x \bigwedge_{\alpha \in u} \varphi_\alpha(x, a_\alpha) \right\}.$$

Then d is as desired. \square

Lemma 6.12 (Transfer lemma). *Suppose that we have the following data:*

- (1) \mathcal{D} is a regular, λ^+ -excellent filter on I ,
- (2) \mathcal{D}_1 is an ultrafilter on I extending \mathcal{D} , and is $|T|^+$ -good,
- (3) \mathfrak{B} is a Boolean algebra,
- (4) $\mathbf{j}: \mathcal{P}(I) \rightarrow \mathfrak{B}$ is a surjective homomorphism with $\mathcal{D} = \mathbf{j}^{-1}(\{1_{\mathfrak{B}}\})$,
- (5) $\mathcal{D}_* = \{\mathbf{b} \in \mathfrak{B}: \text{if } \mathbf{j}(A) = \mathbf{b} \text{ then } A \in \mathcal{D}_1\}$,
- (6) $M \models T$ is λ^+ -saturated.

Then the following two statements are true.

- (A) Let $\langle A_u: u \in [\lambda]^{<\aleph_0} \rangle \subseteq \mathcal{P}(I)$ be the image of an accurate weak distribution of some φ -type from M^I/\mathcal{D}_1 . Then $\langle \mathbf{j}(A_u): u \in [\lambda]^{<\aleph_0} \rangle \subseteq \mathfrak{B}$ is a $(\lambda, \mathfrak{B}, T, \varphi)$ -possibility pattern.
- (B) Let $\langle \mathbf{a}_u: u \in [\lambda]^{<\aleph_0} \rangle$ be a $(\lambda, \mathfrak{B}, T, \varphi)$ -possibility pattern. Then there exists a sequence $\bar{\mathbf{B}} = \langle B_u: u \in [\lambda]^{<\aleph_0} \rangle \subseteq \mathcal{P}(I)$ so that $\mathbf{j}(B_u) = \mathbf{a}_u$ for each $u \in [\lambda]^{<\aleph_0}$ and so that $\bar{\mathbf{B}}$ is an accurate weak distribution of some φ -type in M^I/\mathcal{D}_1 .

Proof. (A) Let $\bar{A} = \langle A_u: u \in [\lambda]^{<\aleph_0} \rangle$ be an accurate weak distribution of a given φ -type p . Let $\bar{\mathbf{a}} = \langle \mathbf{a}_u: u \in [\lambda]^{<\aleph_0} \rangle$ be a sequence of elements of \mathfrak{B}^+ given by $\mathbf{a}_u = \mathbf{j}(A_u)$.

We check that $\langle \mathbf{a}_u: u \in [\lambda]^{<\aleph_0} \rangle$ is a $(\lambda, \mathfrak{B}, T, \varphi)$ -possibility pattern. Conditions (1)–(3) of Definition 6.1 follow from the definitions of \bar{A} and \mathbf{j} . Recall that for condition (4) we need to check that:

if $u_* \in [\lambda]^{<\aleph_0}$ and $\mathbf{b} \in \mathfrak{B}^+$ satisfies

$$(u \subseteq u_* \implies ((\mathbf{b} \leq \mathbf{a}_u) \vee (\mathbf{b} \leq 1 - \mathbf{a}_u))) \wedge (\alpha \in u_* \implies \mathbf{b} \leq \mathbf{a}_{\{\alpha\}})$$

then we can find a model $M_0 \models T$ and $c_i \in M$ for $i \in u_*$ so that for every $u \subseteq u_*$,

$$M_0 \models (\exists x) \bigwedge_{i \in u} \varphi(x; c_i) \quad \text{iff} \quad \mathbf{b} \leq \mathbf{a}_u.$$

Let such u_* and \mathbf{b} be given. Choose $B \in \mathcal{P}(I)$ so that $\mathbf{j}(B) = \mathbf{b}$. Then $B \neq \emptyset \pmod{\mathcal{D}}$ since \mathbf{j} is a homomorphism. Moreover, if σ, τ partition $\mathcal{P}(u_*)$ so that

$$\mathfrak{B} \models \bigwedge_{u \in \sigma} \mathbf{b} \leq \mathbf{a}_u \wedge \bigwedge_{v \in \tau} \mathbf{b} \leq 1 - \mathbf{a}_v$$

then we likewise have that

$$B \cap \left(\bigcap_{u \in \sigma} A_u \setminus \bigcup_{v \in \tau} A_v \right) \neq \emptyset \quad \text{mod } \mathcal{D}.$$

Choose any t belonging to this nonempty set. Then by the accuracy of \bar{A} , let $c_i = a_i[t]$ and then $\{c_i: i \in u_*\}$ provide the desired witnesses to the inset equation above. So $\langle \mathbf{a}_u: u \in [\lambda]^{<\aleph_0} \rangle$ is a $(\lambda, \mathfrak{B}, T, \varphi)$ -possibility pattern, as desired.

(B) Let $\bar{\mathbf{a}} = \langle \mathbf{a}_u: u \in [\lambda]^{<\aleph_0} \rangle$ be a $(\lambda, \mathfrak{B}, T, \varphi)$ -possibility pattern.

First, by surjectivity of \mathbf{j} , for each $u \in [\lambda]^{<\aleph_0}$ we may choose $A_u \subseteq I$ so that $\mathbf{j}(A_u) = \mathbf{a}_u$. Apply Definition 4.6 to $\bar{A} = \langle A_u: u \in [\lambda]^{<\aleph_0} \rangle$ to obtain an excellent refinement $\bar{B} = \langle B_u: u \in [\lambda]^{<\aleph_0} \rangle$. As $A_u = B_u \bmod \mathcal{D}$, $\mathbf{j}(A_u) = \mathbf{j}(B_u)$. To prove our claim, we now look for elements $\langle c_\epsilon: \epsilon < \lambda \rangle$ in M^I/\mathcal{D} so that \bar{B} is an accurate weak distribution of the type $p(x) = \{\varphi(x, c_\epsilon): \epsilon < \lambda\}$. We define c_ϵ by first choosing $c_{t,\epsilon}$ for each $t \in I$ as follows.

For each $t \in I$, let $\mathcal{U}_t = \{\epsilon < \lambda: t \in B_{\{\epsilon\}}\}$. We will want to find $c_\epsilon[t]$, for $\epsilon \in \mathcal{U}_t$, such that for every finite $u \subseteq \mathcal{U}_t$,

$$M \models \exists x \bigwedge \{\varphi(x; c_{t,\epsilon}): \epsilon \in u\} \iff t \in B_u.$$

As the model M is λ^+ -saturated, by compactness, it suffices to show that we can choose such $c_\epsilon[t]$ for an arbitrary but fixed t and finite $u_* = \{\epsilon_0, \dots, \epsilon_{n-1}\} \subseteq \mathcal{U}_t$. Let w_0, \dots, w_k list the subsets u of u_* so that $t \in B_u$, and let v_0, \dots, v_m list the subsets u of u_* so that $t \notin B_u$. In this notation, we are looking for elements a_0, \dots, a_{n-1} of M so that:

$$M \models \bigwedge_{i \leq k} \left(\exists x \bigwedge_{\ell \in w_i} \varphi(x; a_\ell) \right) \wedge \bigwedge_{j \leq m} \left(\neg \exists x \bigwedge_{\ell \in v_j} \varphi(x; a_j) \right).$$

First observe that we can always find $\mathbf{b} \in \mathfrak{B} \setminus \{0\}$ so that $\mathbf{b} \leq \bigcap_{i \leq k} \mathbf{b}_{w_i}$ while $\mathbf{b} \cap \left(\bigcup_{j \leq m} \mathbf{b}_{v_j} \right) = 0$. Why? Suppose for a contradiction that there is no such \mathbf{b} . Consider the corresponding Boolean term $\sigma(x_{\mathcal{P}(u_*)}) = \bigcap_i x_{w_i} \cap \bigcap_j 1 - x_{v_j}$. Let us check whether $\sigma \in \Lambda_{\mathcal{D}, \bar{\mathbf{b}}}$. If $u = u_*$, the term is $0_{\mathfrak{B}}$ by our assumption for a contradiction. If $u \subseteq u_*$ misses some w_i , then the expression is clearly $0_{\mathfrak{B}}$. But recall that the list of w_i includes all singleton sets, by Definition 6.1. So if $u \subsetneq u_*$ we obtain $0_{\mathfrak{B}}$ as well. This shows that $\sigma \in \Lambda_{\mathcal{D}, \bar{\mathbf{b}}}$. As \bar{B} is excellent, $\sigma(\bar{B}|_{\mathcal{P}(u_*)}) = 0$. This contradicts the choice of t and completes the observation.

Since we can always find such $\mathbf{b} \in \mathfrak{B}$, apply the definition of “possibility pattern” 6.1 to choose the desired parameters.

Thus for each $t \in I$ we are able to choose $\{c_{t,\epsilon}: \epsilon \in \mathcal{U}_t\}$ as described. For $\epsilon \notin \mathcal{U}_t$, let $c_{t,\epsilon}$ be arbitrary. Then for each $\epsilon < \lambda$ let $c_\epsilon = \prod_{t \in I} c_{t,\epsilon}/\mathcal{D}_1$. The type $p(x) = \{\varphi(x, c_\epsilon): \epsilon < \lambda\}$ has accurate weak distribution $\langle B_u: u \in [\lambda]^{<\aleph_0} \rangle$, which completes the proof. \square

Theorem 6.13 (Separation of variables). *Suppose that we have the following data:*

- (1) \mathcal{D} is a regular, λ^+ -excellent filter on I ,
- (2) \mathcal{D}_1 is an ultrafilter on I extending \mathcal{D} , and is $|T|^+$ -good,
- (3) \mathfrak{B} is a Boolean algebra,
- (4) $\mathbf{j}: \mathcal{P}(I) \rightarrow \mathfrak{B}$ is a surjective homomorphism with $\mathcal{D} = \mathbf{j}^{-1}(\{1_{\mathfrak{B}}\})$,
- (5) $\mathcal{D}_* = \{\mathbf{b} \in \mathfrak{B}: \text{if } \mathbf{j}(A) = \mathbf{b} \text{ then } A \in \mathcal{D}_1\}$.

Then the following are equivalent:

- (A) \mathcal{D}_* is $(\lambda, \mathfrak{B}, T)$ -moral, i.e. moral for each formula φ of T .
- (B) For any λ^+ -saturated model $M \models T$, M^I/\mathcal{D}_1 is λ^+ -saturated.

Proof. First we note that it suffices to replace the conclusion of (B) with “ M^λ/\mathcal{D}_1 is λ^+ -saturated for φ -types, for all formulas φ of T ”, by [Fact 6.6](#) (in the main case of interest for Keisler’s order) or [Corollary 6.7](#) (in general). Thus in what follows, we concentrate on φ -types. Note also that any regular ultrafilter is \aleph_1 -good, thus (2) is always satisfied in the main case of interest, countable theories.

(A) \implies (B) Suppose that \mathcal{D}_* is $(\lambda, \mathfrak{B}, T)$ -moral, and we would like to show that M^λ/\mathcal{D}_1 is λ^+ -saturated. Let $p = \{\varphi(x, a_i) : i < \lambda\}$ be the type in question, and let $\bar{A} = \langle A_u : u \in [\lambda]^{<\aleph_0} \rangle$ be an accurate distribution of p , thus a sequence of elements of \mathcal{D}_1 . It will suffice to show that \bar{A} has a multiplicative refinement.

By (A) of the Transfer [Lemma 6.12](#), writing \mathbf{a}_u for $\mathbf{j}(A_u)$, we have that $\langle \mathbf{a}_u : u \in [\lambda]^{<\aleph_0} \rangle \subseteq \mathfrak{B}$ is a $(\lambda, \mathfrak{B}, T, \varphi)$ -possibility pattern. By hypothesis (5) each $\mathbf{a}_u \in \mathcal{D}_*$.

We had assumed that \mathcal{D}_* is $(\lambda, \mathfrak{B}, T)$ -moral, thus it contains a multiplicative refinement $\bar{\mathbf{b}} = \langle \mathbf{b}_u : u \in [\lambda]^{<\aleph_0} \rangle$ of $\bar{\mathbf{a}}$. Choose $\bar{B} = \langle B_u : u \in [\lambda]^{<\aleph_0} \rangle$ so that $B_u \subseteq A_u$ and $\mathbf{j}(B_u) = \mathbf{b}_u$, for $u \in [\lambda]^{<\aleph_0}$. Then \bar{B} is a sequence of elements of \mathcal{D}_1 and is multiplicative modulo \mathcal{D} . Applying excellence of \mathcal{D} , we may replace the sequence \bar{B} with a $[\lambda]^{<\aleph_0}$ -indexed sequence \bar{C} which refines \bar{B} , whose elements belong to \mathcal{D}_1 , and which is truly multiplicative (by conditions (1), (2), (3) of [Definition 4.6](#), respectively). A fortiori, \bar{C} is a multiplicative refinement of \bar{A} , which completes the proof.

(B) \implies (A) Suppose that M^I/\mathcal{D} is λ^+ -saturated and $\varphi = \varphi(x; y)$ is a formula in the language of T , recalling that $\ell(y)$ need not be 1. We will show that \mathcal{D}_* is $(\lambda, \mathfrak{B}, T, \varphi)$ -moral. Let $\bar{\mathbf{a}} = \langle \mathbf{a}_u : u \in [\lambda]^{<\aleph_0} \rangle$ be a $(\lambda, \mathfrak{B}, T, \varphi)$ -possibility and we look for a multiplicative refinement.

By (B) of the Transfer [Lemma 6.12](#) there exists $\bar{A} = \langle A_u : u \in [\lambda]^{<\aleph_0} \rangle \subseteq \mathcal{P}(I)$ so that $\mathbf{j}(A_u) = \mathbf{a}_u$ for each $u \in [\lambda]^{<\aleph_0}$ and so that \bar{A} is an accurate weak distribution of some φ -type p . By definition of \mathcal{D}_1 , assumption (5) of the theorem, \bar{A} is in fact an accurate distribution. Thus p is a consistent type in M^I/\mathcal{D} , therefore by our assumption (B) it is realized. Let α be such a realization. Then the sequence $\bar{\mathbf{b}}$ defined by $\mathbf{b}_u = \mathbf{j}(\{t \in I : M \models \varphi(\alpha[t], c_{t,\epsilon})\})$ for $u \in [\lambda]^{<\aleph_0}$ is the image of a multiplicative refinement of \bar{A} , so will be a sequence of elements of \mathcal{D}_* (thus of \mathfrak{B}^+) as well as a multiplicative refinement of $\bar{\mathbf{a}}$. This completes the proof. \square

Often we do not need to keep track of all formulas or patterns; some much smaller “critical set” will suffice for morality or saturation.

Definition 6.14 (*Critical sets*). Say that $\mathcal{C}_T = \{\varphi_i : i < i_* \leq |\mathcal{L}(T)|\}$ is a *critical set of formulas for T* if whenever $\lambda \geq \aleph_0$, \mathcal{D} is a regular ultrafilter on λ which is $|T|^+$ -good and $M \models T$, we have that M^λ/\mathcal{D} is λ^+ -saturated if and only if it is λ^+ -saturated for φ -types for all $\varphi \in \mathcal{C}_T$.

7. Lemmas for existence

In this section we develop some machinery which will streamline the existence proof for excellent filters, [Theorem 8.1](#). See [Discussion 7.9](#) below for an organizational discussion of the aims of this section, which we postpone until after several definitions.

We begin by recalling *independent families of functions*, a useful tool for keeping track of the remaining decisions in filter construction.

Definition 7.1. Given a filter \mathcal{D} on λ , we say that a family \mathcal{F} of functions from λ into λ is *independent mod \mathcal{D}* if for every $n < \omega$, distinct f_0, \dots, f_{n-1} from \mathcal{F} and choice of $j_\ell \in \text{Range}(f_\ell)$,

$$\{\eta < \lambda : \text{for every } i < n, f_i(\eta) = j_i\} \neq \emptyset \text{ mod } \mathcal{D}.$$

Theorem C. (See Engelking and Karłowicz [5, Theorem 3], see also Shelah [20, Theorem A1.5, p. 656].) For every $\lambda \geq \aleph_0$ there exists a family \mathcal{F} of size 2^λ with each $f \in \mathcal{F}$ from λ onto λ so that \mathcal{F} is independent modulo the empty filter (alternately, by the filter generated by $\{\lambda\}$).

Corollary 7.2. For every $\lambda \geq \aleph_0$ there exists a regular filter \mathcal{D} on λ and a family \mathcal{F} of size 2^λ which is independent modulo \mathcal{D} .

Definition 7.3. Let \mathfrak{B} be a Boolean algebra. $CC(\mathfrak{B})$ is the smallest regular cardinal λ so that any maximal antichain of \mathfrak{B} has cardinality less than λ . If \mathcal{D} is a filter on I , by $CC(B(\mathcal{D}))$ we will mean $CC(B)$ for $B = \mathcal{P}(I)/\mathcal{D}$.

Fact 7.4. (See [20, p. 359].) Suppose \mathcal{D} is a maximal filter on I modulo which \mathcal{F} is independent. Then $CC(B(\mathcal{D})) = \aleph_0$ iff for only finitely many $f \in \mathcal{F}$ is $|\text{Range}(f)| > 1$, and for no $f \in \mathcal{F}$ is $|\text{Range}(f)| = \aleph_0$. Otherwise $CC(B(\mathcal{D}))$ is the first regular cardinal $\lambda > \aleph_0$ so that $f \in \mathcal{F}$ implies $|\text{Range}(f)| < \lambda$.

The following definition, “good triple”, is in current use, so we keep the name here and note that it does not imply that the filter is good in the sense of Definition 3.6 (though this should not cause confusion). As usual, omitting “pre-” means being maximal for the given property.

Definition 7.5 (Good triples). (Cf. [20, Chapter VI].) The triple $(I, \mathcal{D}, \mathcal{G})$ is (λ, κ) -pre-good when:

- (1) I is an infinite set of cardinality λ ,
- (2) \mathcal{D} is a filter on I ,
- (3) \mathcal{G} is a family of functions from I to κ ,
- (4) for each function h from some finite $\mathcal{G}_h \subseteq \mathcal{G}$ to κ so that $g \in \mathcal{G}_h \implies h(g) \in \text{Range}(g)$, we have that $A_h \neq \emptyset \text{ mod } \mathcal{D}$, where

$$A_h = \{t \in I : g \in \mathcal{G}_h \implies g(t) = h(g)\},$$

- (5) $\text{Fin}(\mathcal{G}) = \{h : h \text{ as just defined with } \text{dom}(h) \text{ finite}\}$,
- (6) $\text{Fin}_s(\mathcal{G}) = \{A_h : h \in \text{Fin}(\mathcal{G})\}$.

We omit “pre-” when \mathcal{D} is maximal subject to these conditions.

Observation 7.6. If $(I, \mathcal{D}, \mathcal{G})$ is a good triple, then $\text{Fin}_s(\mathcal{G})$ is dense in $\mathcal{P}(I) \text{ mod } \mathcal{D}$.

Proof. We prove this in a more general case, Observation 7.20 below. \square

The next fact summarizes how such families allow us to construct ultrafilters; for more details, see [20, Chapter VI, Section 3].

Fact 7.7. (See [20, Lemma 3.18, p. 360].) Suppose that \mathcal{D} is a maximal filter modulo which $\mathcal{F} \cup \mathcal{G}$ is independent, \mathcal{F} and \mathcal{G} are disjoint, the range of each $f \in \mathcal{F} \cup \mathcal{G}$ is of cardinality less than $\text{cof}(\alpha)$, $\text{cof}(\alpha) > \aleph_0$, $\mathcal{F} = \bigcup_{\eta < \alpha} \mathcal{F}_\eta$, the sequence $\langle \mathcal{F}_\eta : \eta < \alpha \rangle$ is increasing, and let $\mathcal{F}^\eta = \mathcal{F} \setminus \mathcal{F}_\eta$. Suppose, moreover, that \mathcal{D}_η ($\eta < \alpha$) is an increasing sequence of filters which satisfy:

- (i) Each D_η is generated by \mathcal{D} and sets supported mod \mathcal{D} by $\text{Fin}_s(\mathcal{F}_\eta \cup \mathcal{G})$.
- (ii) $\mathcal{F}^\eta \cup \mathcal{G}$ is independent modulo D_η .
- (iii) D_η is maximal with respect to (i), (ii).

Then:

- (1) $D^* := \bigcup_{\eta < \alpha} D_\eta$ is a maximal filter modulo which \mathcal{G} is independent.
- (2) If \mathcal{G} is empty, then D^* is an ultrafilter, and for each $\eta < \alpha$, (ii) is satisfied whenever D_η is nontrivial and satisfies (i).
- (3) If $\eta < \alpha$ and we are given D'_η satisfying (i), (ii) we can extend it to a filter satisfying (i), (ii), (iii).
- (4) If $f \in \mathcal{F}^\eta$ then $\{f^{-1}(t)/D_\eta : t \in \text{Range}(f)\}$ is a partition in $B(D_\eta)$.

Definition 7.8. Denote by $\mathfrak{B}_{\chi, \mu}$ the completion of the Boolean algebra generated by $\{x_{\alpha, \epsilon} : \alpha < \chi, \epsilon < \mu\}$ freely except for the conditions $\alpha < \chi \wedge \epsilon < \zeta < \mu \implies x_{\alpha, \epsilon} \cap x_{\alpha, \zeta} = 0$.

Discussion 7.9. In our main construction, we first build an excellent filter whose quotient Boolean algebra admits a surjective homomorphism onto \mathfrak{B} , and then construct an ultrafilter on this \mathfrak{B} using the method of independent functions.

For the first stage, the set of tools developed beginning with [Definition 7.14](#) will allow us to upgrade the notion of “ \mathcal{G} is independent mod \mathcal{D} ” to take into account a background Boolean algebra \mathfrak{B} which retains a specified amount of freedom. This will be used in the construction of [Theorem 8.1](#), where the intention will be that (by the end of the construction) we will have the desired map to \mathfrak{B} .

For the second stage, [Definition 7.10](#) through [Observation 7.13](#), which we now discuss, are direct translations of the facts about families of independent functions, for the purposes of constructing ultrafilters on $\mathfrak{B} = \mathfrak{B}_{2^\lambda, \mu}$.

Thus, in the case where \mathfrak{B} from the first stage is taken to be $\mathfrak{B}_{2^\lambda, \mu}$, the Boolean algebra \mathfrak{B} occurring throughout this section is essentially the same object, but its different uses correspond to the different stages in the proof.

Definition 7.10 (*Good Boolean triples*). The “Boolean” triple $(\mathfrak{B}, \mathcal{D}, \mathcal{G})$ is $(2^\lambda, \kappa)$ -pre-good when:

- (1) $\mathfrak{B} = \mathfrak{B}_{2^\lambda, \kappa}$, so in particular \mathfrak{B} has the κ^+ -c.c.,
- (2) \mathcal{D} is a filter on \mathfrak{B} ,
- (3) $\mathcal{G} = \{\{\mathbf{b}_{i, \epsilon} : \epsilon < \mu\} : i < \kappa\}$ is a set of partitions of \mathfrak{B} ,
- (4) for each function h from some finite $\sigma \subseteq \kappa$ to κ we have that $A_h \neq \emptyset \text{ mod } \mathcal{D}$, where

$$A_h = \bigcap \{\mathbf{b}_{i, \epsilon} : i \in \text{dom}(h), h(i) = \epsilon\},$$

- (5) $\text{Fin}(\mathcal{G}) = \{h : h \text{ as just defined with } \text{dom}(h) \text{ finite}\}$,
- (6) $\text{Fin}_s(\mathcal{G}) = \{A_h : h \in \text{Fin}(\mathcal{G})\}$.

We omit “pre-” when \mathcal{D} is maximal subject to these conditions.

Remark 7.11. Notice that according to our notation, “Boolean” triples are $(2^\lambda, \dots, \dots)$ -good where ordinary triples $(I, \mathcal{D}, \mathcal{G})$ would have been (λ, \dots, \dots) -good. This should not cause con-

fusion. Throughout the paper we consider independent families of size 2^λ and index sets of size λ .

Definition 7.12. Say that \mathcal{G} is a *set of independent partitions of \mathfrak{B} mod \mathcal{D}* when $(\mathfrak{B}, \mathcal{D}, \mathcal{G})$ is a pre-good Boolean triple as in [Definition 7.10](#).

Observation 7.13. Let $(\mathfrak{B}, \mathcal{D}, \mathcal{G})$ be a $(2^\lambda, \mu)$ -good Boolean triple. Let $\langle \mathbf{b}_j : j < \lambda \rangle$ be a sequence of elements of \mathfrak{B} which are each nonzero modulo \mathcal{D} . Then there exists a set $\mathcal{G}' \subseteq \mathcal{G}$ of independent partitions, $|\mathcal{G}'| \leq \lambda$ so that for each $j < \lambda$ the element \mathbf{b}_j is supported in $\text{Fin}_s(\mathcal{G}')$.

In particular, in the notation of [Definition 7.8](#) this is true when \mathcal{G} is $\{\{\mathbf{x}_{\alpha,\epsilon} : \alpha < \mu\} : i < 2^\lambda\}$ and $\mathcal{D} = \{1_{\mathfrak{B}}\}$.

Proof. For each $j < \lambda$, choose a partition $\mathfrak{P}_j = \{A_{h_\ell^j} : \ell < \mu\}$ of $\text{Fin}_s(\mathcal{G})$ supporting \mathbf{b}_j . [How? We try to do this by induction on $\ell < \mu^+$ using the translation of [Observation 7.6](#). At odd steps choose new elements for the partition in the “remainder” inside \mathbf{b} , at even steps choose new elements in the “remainder” inside $1_{\mathfrak{B}} \setminus \mathbf{b}$, and at limits take unions. By the μ^+ -c.c. any such partition will stop at some bounded stage below μ^+ as the remainders become empty, and then we may renumber so the partition is indexed by $\ell < \mu$.]

Let $X_j = \{i < 2^\lambda : (\exists \ell < \mu) (i \in \text{dom}(h_\ell^j))\}$ be the set of indices for “rows” in \mathcal{G} used in the partition for \mathbf{b}_j . Let $\mathcal{G}' = \{\mathbf{b}_{i,\epsilon} : \epsilon < \mu, (\exists j < \lambda) (i \in X_j)\}$ collect all such “rows”. Then $|\mathcal{G}'| \leq \lambda$, and each \mathbf{b}_j is supported by $\text{Fin}_s(\mathcal{G}')$ by construction, which completes the proof. \square

This completes the introduction of notation for building ultrafilters on a specified Boolean algebra (the step corresponding to “morality”). We now introduce notation for the complementary step, corresponding to “excellence”.

Definition 7.14 (*Boolean algebra constraints on an independent family of functions*). Fix $\lambda \geq \aleph_0$ and an index set I , $|I| = \lambda$, \mathcal{D}_0 a filter on I . Let \mathfrak{B} be a complete Boolean algebra of cardinality $\leq 2^\lambda$ with $CC(\mathfrak{B}) \leq \lambda^+$, $\mathcal{G} \subseteq {}^\lambda 2$ a family of functions independent modulo \mathcal{D}_0 , and $\mathcal{D} \supseteq \mathcal{D}_0$ a filter. Fix in advance a choice of enumeration of $\langle \mathbf{b}_\gamma : \gamma < \gamma_* \rangle$ of $\mathfrak{B} \setminus \{0_{\mathfrak{B}}\}$ and an enumeration $\langle g_\gamma : \gamma < \gamma_* \rangle$ of \mathcal{G} .

Given this enumeration, which will remain fixed for the remainder of the argument, set $B_\gamma = g_\gamma^{-1}\{1\}$ for $\gamma < \gamma_*$.

Let $[\mathcal{G}|\mathfrak{B}] = \{X : X \subseteq I, I \setminus X \in \text{Cond}\}$, where

$$\text{Cond} = \left\{ \sigma(B_{\gamma_0}, \dots, B_{\gamma_{n-1}}) : \sigma(x_0, \dots, x_{n-1}) \text{ is a Boolean term and } \right. \\ \left. \gamma_0, \dots, \gamma_{n-1} < \gamma_* = |\mathfrak{B}| \text{ are so that } \mathfrak{B} \models “\sigma(\mathbf{b}_{\gamma_0}, \dots, \mathbf{b}_{\gamma_{n-1}}) = 0” \right\}.$$

Say that \mathcal{G} is *constrained by \mathfrak{B} modulo \mathcal{D}* when, for some choice of enumeration of \mathfrak{B} and of \mathcal{G} inducing a definition of $\{B_\gamma : \gamma < \gamma_*\}$, we have that \mathcal{D} contains the filter generated by $[\mathcal{G}|\mathfrak{B}]$.

Remark 7.15. Remarks on [Definition 7.14](#): First, we could have taken \mathcal{G} to be any family of functions with range of size ≥ 2 , e.g. μ . Second, this definition looks towards [Observation 7.19](#) and [Observation 7.17](#) below.

In the main case of interest, the constraints on \mathcal{G} given by the Boolean algebra \mathfrak{B} are the only barriers to independence:

Definition 7.16. In the notation of [Definition 7.14](#), let \mathcal{D} be a filter on I , $|I| = \lambda$.

- (1) Suppose that \mathcal{G} is constrained by \mathfrak{B} modulo \mathcal{D} . Fix enumerations of \mathcal{G} , \mathfrak{B} witnessing this.
- (2) Let $\text{Fin}(\mathcal{G}) = \{h: \text{dom}(h) \subseteq \mathcal{G}, |\text{dom}(h)| < \aleph_0, g \in \text{dom}(h) \implies h(g) \in \text{Range}(g)\}$.
- (3) Say that $h \in \text{Fin}(\mathcal{G})$ is *prevented* by \mathfrak{B} when $h = \{(g_\gamma, i_\gamma): \gamma \in \sigma \in [\gamma_*]^{<\aleph_0}, i_\gamma \in \{0, 1\} = \text{Range}(g_\gamma)\}$ and we have that

$$\mathfrak{B} \models \bigcap_{\gamma \in \sigma} (\mathbf{b}_\gamma)^{i_\gamma} = 0$$

recalling [Convention 4.1](#) on exponentiation.

- (4) Now define
 - (a) $\text{Fin}(\mathcal{G}|\mathfrak{B}) = \{h: h \in \text{Fin}(\mathcal{G}) \text{ and } h \text{ is not prevented by } \mathfrak{B}\}$,
 - (b) $\text{Fin}_s(\mathcal{G}|\mathfrak{B}) = \{A_h: h \in \text{Fin}(\mathcal{G}|\mathfrak{B})\}$.
- (5) Say that $(I, \mathcal{D}, \mathcal{G}|\mathfrak{B})$ is a (λ, μ) -pre-good triple when for some enumeration of \mathcal{G} and \mathfrak{B} :
 - (a) I is an infinite set of cardinality λ ,
 - (b) \mathcal{D} is a regular filter on I ,
 - (c) \mathcal{G} is a family of functions from I to 2,
 - (d) \mathfrak{B} is a μ^+ -c.c. complete Boolean algebra, $|\mathfrak{B}| \leq 2^\lambda$,
 - (e) \mathcal{G} is constrained by \mathfrak{B} modulo \mathcal{D} ,
 - (f) for each $A_h \in \text{Fin}_s(\mathcal{G}|\mathfrak{B})$, $A_h \neq \emptyset \text{ mod } \mathcal{D}$,
 - (g) we omit “pre-” when \mathcal{D} is maximal subject to these conditions.
- (6) Say that $(I, \mathcal{D}, (\mathcal{G}|\mathfrak{B}) \cup \mathcal{F})$ is a (λ, κ, μ) -pre-good triple when:
 - (a) $\mathcal{F} \subseteq {}^I \kappa$, $\mathcal{G} \subseteq {}^I 2$, $\mathcal{F} \cap \mathcal{G} = \emptyset$,
 - (b) $(I, \mathcal{D}, \mathcal{G}|\mathfrak{B})$ is a (λ, μ) -pre-good triple, so in particular \mathfrak{B} is a μ^+ -c.c. Boolean algebra,
 - (c) for each $A_h \in \text{Fin}_s(\mathcal{G}|\mathfrak{B})$ and each $A_j \in \text{Fin}_s(\mathcal{F})$, $A_h \cap A_j \neq \emptyset \text{ mod } \mathcal{D}$.
 (N.b. (λ, κ, μ) means $\lambda = |I|$, κ is the range of $f \in \mathcal{F}$, and \mathfrak{B} has the μ^+ -c.c.)

In the current paper, we focus on the case where $\mu < \lambda \leq 2^\mu$, \mathfrak{B} has the μ^+ -c.c., and $\mathcal{F} \subseteq {}^I \lambda$. To simplify notation, we will write “ (λ, μ) -pre-good triple” or “ (λ, μ) -good triple” for this case, or simply “pre-good” and “good” when the cardinal constraints are clear from the context.

The next observation verifies that constraint by a Boolean algebra still yields a filter.

Observation 7.17. Let $\lambda, I, \mathcal{D}, \mathcal{G}, \mathfrak{B}$ be as in [Definition 7.16](#). Suppose \mathcal{F} is a family of functions from λ onto μ , $\mu \leq \lambda$, so that $\mathcal{F} \cap \mathcal{G} = \emptyset$ and $(I, \mathcal{D}, \mathcal{G} \cup \mathcal{F})$ is a pre-good triple, so in particular $\mathcal{G} \cup \mathcal{F}$ is independent mod \mathcal{D} .

Then letting \mathcal{D}_1 be the filter generated by $\mathcal{D} \cup [\mathcal{G}|\mathfrak{B}]$, in the notation of [Definition 7.14](#), we have that:

- (I) \mathcal{D}_1 is a filter on I , and
- (II) for every $h \in \text{Fin}(\mathcal{F})$ and $\gamma < \gamma_*$, $A_h \cap B_\gamma \neq \emptyset \text{ mod } \mathcal{D}_1$.

Proof. Since Cond is closed under finite disjunction it suffices to show that any one of its elements $\sigma(\bar{B})$ has \mathcal{D}_0 -nontrivial complement. To see this, put the negation of the corresponding Boolean term, $\neg\sigma(\bar{x})$, in disjunctive normal form. Since $\mathfrak{B} \models \neg\sigma(\mathbf{b}_{\gamma_0}, \dots, \mathbf{b}_{\gamma_{n-1}}) = 1_{\mathfrak{B}}$, we can choose a disjunct τ which is nonzero in \mathfrak{B} . Then $\tau(\bar{B})$ will be a conjunction of literals, from which we can inductively construct $A_h \in \text{Fin}(\mathcal{G})$ so that $A_h \subseteq \tau(\bar{B}) \text{ mod } \mathcal{D}_0$, simply by replacing

each literal of the form “ B_{γ_i} ” by the condition $g_{\gamma_i} = 1$ and each literal of the form “ $\neg B_{\gamma_j}$ ” by the condition $g_{\gamma_j} = 0$. Recall that the range of each $g \in \mathcal{G}$ is $\{0, 1\}$. By choice of τ , this h is indeed consistent so $A_h \neq \emptyset \bmod \mathcal{D}_0$ since the family \mathcal{G} is independent. Moreover A_h is contained in $\lambda \setminus \sigma(\mathcal{B})$ by construction. This shows that the complement of any set in Cond contained some element of $\text{Fin}_s(\mathcal{G})$ modulo \mathcal{D}_0 , which completes the proof of (I)–(II). \square

For completeness we spell out that such objects exist.

Corollary 7.18. *Let $\kappa \leq \lambda$ and let \mathfrak{B} be a κ^+ -c.c. complete Boolean algebra. Then there exist \mathcal{D} , \mathcal{F} , \mathcal{G} so that:*

- (1) \mathcal{D} is a regular filter on I , $|I| = \lambda$,
- (2) \mathcal{F} is a family of functions from λ into κ , $|\mathcal{F}| = 2^\lambda$,
- (3) \mathcal{G} is a family of functions from λ into 2 , $|\mathcal{G}| = |\mathfrak{B}|$,
- (4) $\mathcal{F} \cap \mathcal{G} = \emptyset$

and $(I, \mathcal{D}, (\mathcal{G}|\mathfrak{B}) \cup \mathcal{F})$ is a (λ, κ) -good triple.

Proof. Let \mathcal{F}_0 be the independent family given by Corollary 7.2 above. Without loss of generality we can write \mathcal{F}_0 as the disjoint union of \mathcal{F} and \mathcal{G} satisfying (2)–(3). As each $A_h \in \text{Fin}_s(\mathcal{F} \cup \mathcal{G})$ has cardinality λ , $(I, \mathcal{D}_0, \mathcal{F} \cup \mathcal{G})$ remains pre-good for $\mathcal{D}_0 = \{A \subseteq \lambda: |\lambda \setminus A| < \lambda\}$.

Let $\gamma_* = |\mathfrak{B}|$. Let $\langle f_\alpha: \alpha < 2^\lambda \rangle$, $\langle g_\gamma: \gamma < \gamma_* \rangle$, $\langle \mathbf{b}_\gamma: \gamma < \gamma_* \rangle$ list \mathcal{F} , \mathcal{G} , and $\mathfrak{B} \setminus \{0_{\mathfrak{B}}\}$ respectively. Let $B_\gamma = g_\gamma^{-1}\{1\}$ for $\gamma < \gamma_*$, and as usual define the set of conditions:

$$\text{Cond} = \left\{ \sigma(B_{\gamma_0}, \dots, B_{\gamma_{n-1}}): \sigma(x_0, \dots, x_{n-1}) \text{ is a Boolean term and } \right. \\ \left. \gamma_0, \dots, \gamma_{n-1} < \gamma_* = |\mathfrak{B}| \text{ are so that } \mathfrak{B} \models \text{“}\sigma(\mathbf{b}_{\gamma_0}, \dots, \mathbf{b}_{\gamma_{n-1}}) = 0\text{”} \right\}.$$

Let \mathcal{D}_1 be the filter generated by $\mathcal{A} = \{X: X \subseteq \lambda, \lambda \setminus X \in \text{Cond}\} \cup \mathcal{D}_0$. Then by Observation 7.17 \mathcal{D}_1 is a filter on λ and $(I, \mathcal{D}, (\mathcal{G}|\mathfrak{B}) \cup \mathcal{F})$ is (λ, κ) -pre-good. To finish, let $\mathcal{D} \supseteq \mathcal{D}_1$ be maximal subject to the constraint that $(I, \mathcal{D}, (\mathcal{G}|\mathfrak{B}) \cup \mathcal{F})$ is (λ, κ) -pre-good. \square

Observation 7.19. *If $(I, \mathcal{D}, \mathcal{G}|\mathfrak{B})$ is a good triple, then there is a surjective homomorphism $\mathbf{j}: \mathcal{P}(I) \rightarrow \mathfrak{B} = \mathfrak{B}_{2^\lambda, \mu}$ so that $\mathcal{D} = \mathbf{j}^{-1}(\{1_{\mathfrak{B}}\})$.*

Observation 7.20. *If $(I, \mathcal{D}, (\mathcal{G}|\mathfrak{B}) \cup \mathcal{F})$ is a good triple, then $\text{Fin}_s((\mathcal{G}|\mathfrak{B}) \cup \mathcal{F})$ is dense in $\mathcal{P}(I) \bmod \mathcal{D}$.*

Proof. (Just as in the usual proof [20, VI.3].) Recall that the definition of “good triple” assumes that \mathcal{D} is maximal so that $(\mathcal{G}|\mathfrak{B}) \cup \mathcal{F}$ is independent mod \mathcal{D} . Suppose for a contradiction the statement of the claim fails, i.e. that there is some $X \subseteq I$, $X \neq \emptyset \bmod \mathcal{D}$ but for every $A_h \in \text{Fin}_s((\mathcal{G}|\mathfrak{B}) \cup \mathcal{F})$, $A_h \not\subseteq X \bmod \mathcal{D}$. Thus for each such A_h , $A_h \cap (I \setminus X) \neq \emptyset \bmod \mathcal{D}$. Let \mathcal{D}' be the filter generated by $\mathcal{D} \cup \{I \setminus X\}$. Then $(I, \mathcal{D}', (\mathcal{G}|\mathfrak{B}) \cup \mathcal{F})$ is also a good triple, contradicting the assumption about the maximality of \mathcal{D} . \square

With this notation in place, we now give two proofs. Recall that in proving existence of excellent filters, we will want on the one hand to ensure the quotient of $\mathcal{P}(I)$ modulo the final filter is isomorphic to a given complete Boolean algebra \mathfrak{B} , and on the other to ensure existence of excellent refinements. The final two results of the section will form the corresponding inductive steps.

Roughly speaking, the following lemma says that if we have a filter \mathcal{D} on I , a family \mathcal{F} with range λ , a family \mathcal{G} constrained by \mathfrak{B} and a subset X of the index set, we may extend \mathcal{D} to a filter \mathcal{D}' so that X is equivalent modulo \mathcal{D}' to some element of \mathfrak{B} (by condition (d) and completeness) at the cost of $\leq \lambda$ elements of \mathcal{F} .

Lemma 7.21. *Suppose $(I, \mathcal{D}, (\mathcal{G}|\mathfrak{B}) \cup \mathcal{F})$ is a (λ, λ, μ) -good triple. Let $X \subseteq I$. Then there are $\mathcal{D}' \supseteq \mathcal{D}$ and $\mathcal{F}' \subseteq \mathcal{F}$ so that*

- (a) \mathcal{D}' is a filter extending \mathcal{D} ,
- (b) $|\mathcal{F}'| = 2^\lambda$, $|\mathcal{F} \setminus \mathcal{F}'| \leq \lambda$,
- (c) $(I, \mathcal{D}', (\mathcal{G}|\mathfrak{B}) \cup \mathcal{F}')$ is a (λ, λ, μ) -good triple,
- (d) X is supported by $\text{Fin}_s(\mathcal{G}|\mathfrak{B})$ modulo \mathcal{D}' .

Proof. Our strategy is as follows. By inductively consuming functions from \mathcal{F} , we build a partition of I using elements from $\text{Fin}_s(\mathcal{G}|\mathfrak{B})$ which are either entirely inside or entirely outside the fixed set X . The internal approximation at stage α we call J_α^1 , and the external approximation we call J_α^0 . Since X need not be supported by $\text{Fin}_s(\mathcal{G}|\mathfrak{B}) \text{ mod } \mathcal{D}$, we must continually consume functions from \mathcal{F} in order to “clarify the picture” at stage α in a larger filter \mathcal{D}_α , where we can continue to construct the partition. We consume finitely many functions from \mathcal{F} at each successor stage, and at limits take unions. We apply Fact 7.4 to show the construction will stop before λ^+ . When the induction stops, we have our desired partition (d), and this will complete the proof.

More formally, we try to choose by induction on $\alpha < \lambda^+$ objects $J_0^\alpha, J_1^\alpha, \mathcal{F}^\alpha, \mathcal{D}_\alpha$ to satisfy:

- (1) $J_1^\alpha \subseteq \text{Fin}_s(\mathcal{G}|\mathfrak{B})$, and $\bigcup J_1^\alpha \subseteq X \text{ mod } \mathcal{D}_\alpha$,
- (2) $A, A' \in J_1^\alpha \implies A \cap A' = \emptyset \text{ mod } \mathcal{D}_\alpha$,
- (3) $\beta < \alpha \implies J_1^\beta \subseteq J_1^\alpha$,
- (4) $J_0^\alpha \subseteq \text{Fin}_s(\mathcal{G}|\mathfrak{B})$, and $\bigcup J_0^\alpha \subseteq I \setminus X \text{ mod } \mathcal{D}_\alpha$,
- (5) $A, A' \in J_0^\alpha \implies A \cap A' = \emptyset \text{ mod } \mathcal{D}_\alpha$,
- (6) $\beta < \alpha \implies J_0^\beta \subseteq J_0^\alpha$,
- (7) \mathcal{D}_α is a filter extending \mathcal{D} , with $(I, \mathcal{D}_\alpha, (\mathcal{G}|\mathfrak{B}) \cup \mathcal{F}^\alpha)$ a good triple,
- (8) $\beta < \alpha \implies \mathcal{D}_\beta \subseteq \mathcal{D}_\alpha$,
- (9) for α limit, $\mathcal{D}_\alpha = \bigcup \{\mathcal{D}_\beta : \beta < \alpha\}$,
- (10) $\mathcal{F}^\alpha \subseteq \mathcal{F}$, with $\beta < \alpha \implies \mathcal{F}^\alpha \subseteq \mathcal{F}^\beta$,
- (11) for α limit, $\mathcal{F}^\alpha = \bigcap \{\mathcal{F}^\beta : \beta < \alpha\}$,
- (12) for $\alpha = \beta + 1$, $|\mathcal{F}^\beta \setminus \mathcal{F}^\alpha| < \aleph_0$.

For $\alpha = 0$, let $\mathcal{D}_0 = \mathcal{D}$, $\mathcal{F}_0 = \mathcal{F}$. Choose J_1^0, J_0^0 maximal subject to the constraints (1)–(4).

For α limit, define \mathcal{D}_α in accordance with (9), \mathcal{F}^α in accordance with (11). Likewise, let $J_1^\alpha = \bigcup \{J_1^\beta : \beta < \alpha\}$ and let $J_0^\alpha = \bigcup \{J_0^\beta : \beta < \alpha\}$.

For successor stages, we distinguish between even (increase J_0^β) and odd (increase J_1^β).

First consider $\alpha = \beta + 1$. If both $X \setminus J_1^\beta = \emptyset \text{ mod } \mathcal{D}_\beta$ and $(I \setminus X) \setminus J_0^\beta = \emptyset \text{ mod } \mathcal{D}_\beta$, then we satisfy (d) and finish. If $X \setminus J_1^\beta = \emptyset \text{ mod } \mathcal{D}_\beta$, we have finished the construction of $J_1 = J_1^\beta$. So suppose $X \setminus J_1^\beta = \emptyset \text{ mod } \mathcal{D}_\beta$.

Apply Observation 7.20 to find sets $A_h \in \text{Fin}_s(\mathcal{G}|\mathfrak{B})$ and $A_{h'} \in \text{Fin}_s(\mathcal{F})$ so that

$$(A_h \cap A_i) \subseteq (X \setminus J_1^\beta) \text{ mod } \mathcal{D}.$$

Keeping in mind the asymmetry between the roles of \mathcal{F} and \mathcal{G} in this proof, let $\mathcal{F}^\alpha = \mathcal{F}^\beta \setminus \{\text{dom } h'\}$, which satisfies (12) by definition of $\text{Fin}_s(\mathcal{F})$. Now let \mathcal{D}_α be the filter generated by $\mathcal{D}_\beta \cup \{A_{h'}\}$. Clearly this is a filter by condition $(7)_\beta$, and by construction, $(I, \mathcal{D}_\alpha, (\mathcal{G}|\mathfrak{B}) \cup \mathcal{F}^\alpha)$ will satisfy $(7)_\alpha$. Finally, let $J_1^\alpha = J_1^\beta \cup \{A_h\}$ and let $J_0^\alpha = J_0^\beta$.

The case $\alpha = \beta + 2$ is parallel to the odd case but with $J_0^{\beta+1}$, J_0^α replacing J_1^β , J_1^α , and $I \setminus X$ replacing X .

Without loss of generality, let each \mathcal{D}_α be maximal subject to the fact that $(I, \mathcal{D}_\alpha, (\mathcal{G}|\mathfrak{B}) \cup \mathcal{F}^\alpha)$ is a pre-good triple.

Note that for each $\alpha \leq \lambda^+$, $CC(B(\mathcal{D}_\alpha)) \leq \lambda^+$ by condition (7) and [Fact 7.4](#), and moreover $J_0^\alpha \cup J_1^\alpha$ is a set of pairwise disjoint elements of $B(\mathcal{D}_\alpha)$ with $|J_0^\alpha \cup J_1^\alpha| \geq |\alpha|$. Thus the length of this construction is bounded below λ^+ . In other words, at some point $\alpha < \lambda^+$ both $X \setminus J_1^\beta = \emptyset \text{ mod } \mathcal{D}_\alpha$ and $(I \setminus X) \setminus J_0^\beta = \emptyset \text{ mod } \mathcal{D}_\alpha$, and here we take $\mathcal{D}' = \mathcal{D}_\alpha$ to finish the proof. \square

To conclude this section, we show how to construct an excellent refinement.

Claim 7.22. *Suppose $(I, \mathcal{D}, (\mathcal{G}|\mathfrak{B}) \cup \mathcal{F})$ is (λ, λ, μ) -good. Let $f \in \mathcal{F}$, $\mathcal{F}' = \mathcal{F} \setminus \{f\}$, and let $\bar{A} = \langle A_u : u \in [\lambda]^{<\aleph_0} \rangle$ be a sequence of elements of $\mathcal{P}(I)$ so that for each $A_u \in \bar{A}$ and each $A_h \in \text{Fin}_s(\mathcal{F})$, $A_h \cap A_u \neq \emptyset \text{ mod } \mathcal{D}$.*

Then there is a filter $\mathcal{D}' \supseteq \mathcal{D}$ and a sequence $\langle B_u : u \in [\lambda]^{<\aleph_0} \rangle$ of elements of $\mathcal{P}(I)$ satisfying [Definition 4.6](#), namely:

- (1) for each $u \in [\lambda]^{<\aleph_0}$, $B_u \subseteq A_u$,
- (2) for each $u \in [\lambda]^{<\aleph_0}$, $B_u = A_u \text{ mod } \mathcal{D}$,
- (3) if $u \in [\lambda]^{<\aleph_0}$ and $\sigma \in \Lambda = \Lambda_{\mathcal{D}, \bar{A}|_u}$, so $\sigma(\bar{A}|_{\mathcal{P}(u)}) = \emptyset \text{ mod } \mathcal{D}$, then $\sigma(\bar{B}|_{\mathcal{P}(u)}) = \emptyset$

so that, moreover, $(I, \mathcal{D}', (\mathcal{G}|\mathfrak{B}) \cup \mathcal{F}')$ is (λ, λ, μ) -good.

Proof. We proceed in stages.

Step 1: The exceptional sets Y_ϵ . Let $\langle u_\epsilon : \epsilon < \lambda \rangle$ enumerate the finite subsets of λ . For each ϵ let

$$Y_\epsilon = \bigcup \{ \sigma(\bar{A}|_{\mathcal{P}(u_\epsilon)}) : \sigma \text{ a Boolean term and } \sigma(\bar{A}|_{\mathcal{P}(u_\epsilon)}) = \emptyset \text{ mod } \mathcal{D} \}.$$

Then Y_ϵ is a finite union of subsets of λ which are $= \emptyset \text{ mod } \mathcal{D}$, hence $Y_\epsilon = \emptyset \text{ mod } \mathcal{D}$.

Step 2: The role of “below”. Suppose that $\sigma(\bar{x}_{\mathcal{P}(u_\epsilon)}) \in \Lambda_{\mathcal{D}, \bar{A}}$ and $v \subseteq u_\epsilon$. Let \bar{A}' be the sequence given by $A'_w = A_w$ if $w \subseteq v$ and $A'_v = 0_{\mathfrak{B}}$ otherwise. Then also $\sigma(\bar{A}'|_{\mathcal{P}(u_\epsilon)}) \subseteq Y_\epsilon$, by definition of Λ (as 0 is a constant of the language of Boolean algebras).

Step 3: Defining the filter. Now for $u \in [\lambda]^{<\aleph_0}$ define

$$B_u = \bigcup \{ A_u \cap f^{-1}(\epsilon) \setminus Y_\epsilon : \epsilon < \lambda \text{ and } u \subseteq u_\epsilon \}.$$

Then $\langle B_u : u \in [\lambda]^{<\aleph_0} \rangle$ is the proposed refinement. Let \mathcal{D}' be the filter generated by $\mathcal{D} \cup \{X_u : u \in [\lambda]^{<\aleph_0}\}$ where

$$X_u = I \setminus (B_u \Delta A_u).$$

Step 4: The filter is nontrivial and the triple is pre-good. Fix $u = u_\epsilon$. Then $f^{-1}(\epsilon) = f^{-1}(\epsilon) \setminus Y_\epsilon \bmod \mathcal{D}$, so

$$B_u \supseteq A_u \cap f^{-1}(\epsilon) \setminus Y_\epsilon \neq \emptyset \bmod \mathcal{D}$$

where “ $\neq \emptyset$ ” holds by the hypothesis of independence, since $f \in \mathcal{F}$. Likewise we assumed that any $A_h \in \text{Fin}_s(\mathcal{F}')$, $A_u \cap A_h \neq \emptyset \bmod \mathcal{D}$. Recall $\mathcal{F}' = \mathcal{F} \setminus \{f\}$. Since $f \notin \mathcal{F}'$, we therefore have

$$B_u \supseteq A_u \cap A_h \cap (f^{-1}(\epsilon) \setminus Y_\epsilon) \neq \emptyset \bmod \mathcal{D}.$$

Thus \mathcal{D}' is a filter. Now consider $A_{h'} \in \text{Fin}_s(\mathcal{G}|\mathfrak{B})$. There are two cases. If $A_u \cap A_h \cap A_{h'} \neq \emptyset \bmod \mathcal{D}$, then this intersection is contained in $B_u \bmod \mathcal{D}$. Otherwise, $A_h \cap A_{h'} \subseteq (I \setminus A_u) \bmod \mathcal{D}$. In either case, $A_h \cap A_{h'}$ does not nontrivially intersect $(I \setminus (A_u \Delta B_u)) \bmod \mathcal{D}$, and so remains nonempty $\bmod \mathcal{D}'$. This shows that $(I, \mathcal{D}', (\mathcal{G}|\mathfrak{B}) \cup \mathcal{F}')$ is pre-good triple.

Step 5: The sequence \bar{B} is excellent. Write $\bar{B} = \langle B_u : u \in [\lambda]^{<\aleph_0} \rangle$. We have shown (1)–(2) from the statement of the claim. For condition (3), let $u \in [\lambda]^{<\aleph_0}$ and $\sigma(\bar{x}_{\mathcal{P}(u)}) \in \Lambda$ be given. Suppose for a contradiction that there were $t \in \sigma(\bar{B}|_{\mathcal{P}(u)})$. Let $\epsilon_t = f^{-1}(t)$. Then Step 2 in the case $v = u \cap u_{\epsilon_t}$ gives a contradiction.

Step 6: A good triple. To finish, without loss of generality we may take \mathcal{D}' maximal subject to the condition that $(I, \mathcal{D}', (\mathcal{G}|\mathfrak{B}) \cup \mathcal{F}')$ is a pre-good triple. \square

8. Existence

In this section we prove that for any complete λ^+ -c.c. Boolean algebra \mathfrak{B} of cardinality $\leq 2^\lambda$ there is a regular λ^+ -excellent filter \mathcal{D} on λ so that \mathfrak{B} is isomorphic to $\mathcal{P}(\lambda)/\mathcal{D}$.

Theorem 8.1 (*Existence*). *Let $\mu \leq \lambda$ and let \mathfrak{B} be a μ^+ -c.c. complete Boolean algebra of cardinality $\leq 2^\lambda$. Then there exists a regular excellent filter \mathcal{D} on λ and a surjective homomorphism $\mathbf{j} : \mathcal{P}(I) \rightarrow \mathfrak{B} = \mathfrak{B}_{2^\lambda, \mu}$ so that $\mathcal{D} = \mathbf{j}^{-1}(\{1_{\mathfrak{B}}\})$.*

Proof. We give the proof in several stages. Recall that we have identified the index set with λ .

Stage 0: Preliminaries. We begin by choosing $\mathcal{G}, \mathcal{F}, \mathcal{D}_1$ so that $|\mathcal{G}| = |\mathfrak{B}|$, $|\mathcal{F}| = 2^\lambda$, \mathcal{G} is a family of functions from I onto 2, \mathcal{F} is a family of functions from λ onto λ , and $(I, \mathcal{D}_1, (\mathcal{G}|\mathfrak{B}) \cup \mathcal{F})$ is a (λ, λ, μ) -good Boolean triple, in the notation of [Definition 7.16](#). Such triples exist by [Corollary 7.18](#).

Stage 1: Setting up the inductive construction. We now set up the construction of \mathcal{D} , which we build by induction on $\alpha < 2^\lambda$. Recall that we will want to ensure that on the one hand, the final filter \mathcal{D} is excellent, and on the other that the quotient $\mathcal{P}(I)/\mathcal{D}$ is exactly \mathfrak{B} .

We address the issue of the quotient by enumerating $\mathcal{P}(\lambda)$ as $\langle C_\alpha : \alpha < 2^\lambda \rangle$ and ensuring, at odd inductive steps, that the set C_β under consideration has an appropriate image. This suffices by [Observation 7.19](#).

In order to address all possible barriers to excellence, at even inductive steps, we will need an enumeration of all sequences \bar{B} as in [Definition 4.6](#). Say that $\mathbf{x} : \mathcal{P}_{\aleph_0}(\lambda) \rightarrow \mathcal{P}_{\aleph_0}(\gamma_*)$ is an *indexing sequence* whenever

$$u \in [\lambda]^{<\aleph_0} \implies \bigcup \{\mathbf{x}(i) : i \in u\} = \mathbf{x}(u).$$

Let $\langle \mathbf{x}_\alpha : \alpha < 2^\lambda \rangle$ list all indexing sequences, each appearing 2^λ times. Below, given $u \in [\lambda]^{<\aleph_0}$, we will write e.g. “ $\bar{\mathbf{a}}_{\mathbf{x}(\mathcal{P}(u))}$ ” to indicate that the finite sequence of elements of \mathfrak{B} indexed by the image of the finite subsets of u under \mathbf{x} .

Now we choose $\mathcal{D}_{2,\alpha}, \mathcal{F}^\alpha$ by induction on $\alpha \leq 2^\lambda$ so that:

- (1) $\mathcal{D}_{2,\alpha}$ is a filter on λ .
- (2) $\beta < \alpha < 2^\lambda \implies \mathcal{D}_{2,\beta} \subseteq \mathcal{D}_{2,\alpha}$, and α limit implies $\mathcal{D}_{2,\alpha} = \bigcup_{\beta < \alpha} \mathcal{D}_{2,\beta}$.
- (3) $\mathcal{F}^\alpha \subseteq \mathcal{F}, |\mathcal{F}^\alpha| = 2^\lambda$, and $\beta < \alpha \implies \mathcal{F}^\beta \supseteq \mathcal{F}^\alpha$.
- (4) If $h \in \text{Fin}(\mathcal{F}^\alpha)$ and $\gamma < \gamma_*$ then $A_h \cap B_\gamma \neq \emptyset \pmod{\mathcal{D}_{2,\alpha}}$.
- (5) $(I, \mathcal{D}_\alpha, (\mathcal{G}|\mathfrak{B}) \cup \mathcal{F}^\alpha)$ is (λ, λ, μ) -good.
- (6) If $\alpha = 2\beta + 1$, then for some $\gamma < \gamma_*$, $C_\beta = B_\gamma \pmod{\mathcal{D}_{2,\alpha}}$.
- (7) If $\alpha = 2\beta + 2$, if for each $u \in [\lambda]^{<\aleph_0}$ and Boolean term $\sigma = \sigma(\bar{x}_{\mathcal{P}(u)})$ we have that

$$\mathfrak{B} \models \text{“}\sigma(\bar{\mathbf{b}}_{\mathbf{x}(\mathcal{P}(u))}) = 0\text{”} \implies \sigma(\bar{B}_{\mathbf{x}(\mathcal{P}(u))}) = \emptyset \pmod{\mathcal{D}_{2,2\beta+1}},$$

then we can find $\bar{B}_\alpha = \langle B_u^\alpha : u \in [\lambda]^{<\aleph_0} \rangle$ satisfying [Definition 4.6](#).

For $\alpha = 0$ this is trivial: let $\mathcal{D}_{2,\alpha} = \mathcal{D}_1, \mathcal{F}^\alpha = \mathcal{F}$.

For α limit let $\mathcal{D}_{2,\alpha} = \bigcup \{ \mathcal{D}_{2,\beta} : \beta < \alpha \}, \mathcal{F}^\alpha = \bigcap \{ \mathcal{F}^\beta : \beta < \alpha \}$.

For α successor, we distinguish between even and odd.

Stage 2: Odd successor steps. For $\alpha = 2\beta + 1$ we address (5) for the given C_β . If $C_\beta = \emptyset \pmod{\mathcal{D}_{2,2\beta}}$, let $\mathcal{D}_{2,\alpha} = \mathcal{D}_{2,2\beta}$ and finish. Otherwise, apply [Lemma 7.21](#) above in the case where $\mathcal{D} = \mathcal{D}_{2,2\beta}, \mathcal{F} = \mathcal{F}^{2\beta}, X = C_\beta$. Then let $\mathcal{D}_{2,2\beta+1}$ be the filter \mathcal{D}' and let $\mathcal{F}^{2\beta+1}$ be the family \mathcal{F}' returned by that lemma. Without loss of generality, let $\mathcal{D}_{2,2\beta+1}$ be maximal subject to the condition that $(\mathcal{G}|\mathfrak{B}) \cup \mathcal{F}$ remain independent. Note that conditions (3), (4), (5) are guaranteed by the statement of [Lemma 7.21](#).

Stage 3: Even successor steps. For $\alpha = 2\beta + 2$ we address condition (6). Suppose then that we are given an indexing function $\mathbf{x} = \mathbf{x}_\alpha$ and a corresponding sequence $\langle B_{\mathbf{x}(u)} : u \in [\lambda]^{<\aleph_0} \rangle$ of elements of $\mathcal{P}(I)$. If the “if” clause in condition (4) fails, let $\mathcal{D}_{2,\alpha} = \mathcal{D}_{2,2\beta+1}$, and see the bookkeeping remark in the next step. Otherwise, fix $f_* \in \mathcal{F}^{2\beta+1}$ and apply [Claim 7.22](#) above in the case $\mathcal{D} = \mathcal{D}_{2,2\beta+1}, \mathcal{F} = \mathcal{F}^{2\beta+1}, \mathcal{F}^{2\beta+1} \setminus \{f_*\}$ and $\langle A_u : u \in [\lambda]^{<\aleph_0} \rangle = \langle B_{\mathbf{x}(u)} : u \in [\lambda]^{<\aleph_0} \rangle$. To complete Stage 3, let \mathcal{D}_α be the filter \mathcal{D}' returned by [Claim 7.22](#), and let $\mathcal{F}^\alpha = \mathcal{F}^{2\beta+1} \setminus \{f_*\}$. As in Stage 2, the inductive conditions are guaranteed by the statement of that claim.

Stage X: A remark on bookkeeping. Note that once all the elements of the sequence $\langle B_{\mathbf{x}(u)} : u \in [\lambda]^{<\aleph_0} \rangle$ have appeared as elements C_β in the enumeration at odd successor steps, condition (4) will be satisfied by definition of $(I, \mathcal{D}, (\mathcal{G}|\mathfrak{B}) \cup \mathcal{F})$ -good triple. Likewise, since each indexing function (and therefore each potential sequence \bar{B}) occurs cofinally often in our master enumeration, and the cofinality of the construction is greater than λ , we are justified in [Claim 7.22](#) in only adjusting for those instances of Boolean terms which the filter already considers to be small.

Stage 4: Finishing the proof. Since there is no trouble in carrying out the induction, we finish by letting $\mathcal{D} = \mathcal{D}_{2,2^\lambda} = \bigcup \{ \mathcal{D}_{2,\alpha} : \alpha < 2^\lambda \}$. This completes the proof. \square

Discussion 8.2. What is the effect of Section 5 on [Theorem 8.1](#)? For the purposes of the main [Theorem 12.1](#) of the present paper, [Theorem 5.2](#) means we could substitute “regular good filter”

for “regular excellent filter” in [Theorem 8.1](#) above. Then the even steps of the proof could be replaced by the adding of multiplicative refinements as in Kunen’s proof of the existence of good ultrafilters [9]. However, it is essential that we also be able to specify the quotient Boolean algebra, as guaranteed by the odd steps. Beyond the results of the current paper, we believe that excellence is sufficiently interesting in its own right to justify carrying out the proof of [Theorem 8.1](#) in this language.

9. On flexibility

In this section we give the necessary background for the non-saturation claim in our main theorem. That is, we leverage our prior work to show that once we have built a filter \mathcal{D} on λ so that $\mathcal{P}(I)/\mathcal{D}$ has the μ^+ -c.c. for $\mu < \lambda$, no ultrafilter extending \mathcal{D} will saturate any non-simple or non-low theory. (That is, provided it is built by the method of independent families of functions – if an appeal to complete ultrafilters is made, the situation changes, see e.g. Malliaris and Shelah [16, Remark 4.2].)

The main definition in this section is *flexible filter*, due to Malliaris [10]. Roughly speaking, the definition assigns a natural size to any given regularizing family and asks that a flexible filter have regularizing families of arbitrarily small nonstandard size.

Definition 9.1 (*Flexible filters*). (See [10].) Let \mathcal{D} be a regular filter on I , $|I| = \lambda \geq \aleph_0$, and let $X = \langle X_i : i < \mu \rangle$ be a μ -regularizing family for \mathcal{D} . Say that an element $n_* \in {}^I\mathbb{N}$ is \mathcal{D} -nonstandard if for each $n \in \mathbb{N}$, $\{t \in I : (\mathbb{N}, <) \models n_*[t] > n\} \in \mathcal{D}$.

Define the size of X , σ_X to be the element of ${}^I\mathbb{N}$ defined by

$$\sigma_X[t] = |\{i < \mu : t \in X_i\}| \quad \text{for each } t \in I.$$

Say that \mathcal{D} is μ -flexible if for every \mathcal{D} -nonstandard element n_* there is a μ -regularizing family $X \subseteq \mathcal{D}$ so that $\sigma_X \leq n_* \bmod \mathcal{D}$. Otherwise, say that \mathcal{D} is μ -inflexible (or simply: *not μ -flexible*). When $\mu = \lambda$, we will often omit it.

For more on flexibility, see Malliaris [13] and recent work of Malliaris and Shelah [15,16], where it is shown that flexible is consistently weaker than good.

Malliaris [10] had shown that flexibility is detected by non-low theories, that is:

Fact 9.2. (See Malliaris [10, Lemma 1.21].) Let T be non-low, let $M \models T$ and suppose that \mathcal{D} is a λ -regular ultrafilter on I , $|I| = \lambda$ which is not flexible. Then M^I/\mathcal{D} is not λ^+ -saturated.

By a dichotomy theorem of Shelah, any non-simple theory will have either the tree property of the first kind (TP_1 , or equivalently SOP_2) or else of the second kind (TP_2). A consequence of Malliaris’ proof of the existence of a Keisler-minimum TP_2 theory in [13] is that:

Fact 9.3. (See Malliaris [13, Lemma 8.8].) Let \mathcal{D} be a regular ultrafilter on λ . If \mathcal{D} saturates some theory with TP_2 then \mathcal{D} must be flexible.

A consequence of recent work of Malliaris and Shelah on ultrapowers realizing SOP_2 -types is a complementary result.

Fact 9.4. (Rewording of Malliaris and Shelah [17, Claim 3.11] for the level of theories.) Let \mathcal{D} be a regular ultrafilter on λ . If \mathcal{D} saturates some theory with SOP_2 then \mathcal{D} must be flexible.

Combining these three facts we obtain:

Conclusion 9.5. *Let \mathcal{D} be a regular ultrafilter on λ and suppose \mathcal{D} is not flexible. Let T be a theory which is either non-low or non-simple, or both. Then M^λ/\mathcal{D} is not λ^+ -saturated.*

Remark 9.6. (See [15, Observation 10.9].) \mathcal{D} is λ -flexible if and only if whenever $f : \mathcal{P}_{\aleph_0}(\lambda) \rightarrow \mathcal{D}$ is so that $(u, v \in \mathcal{P}_{\aleph_0}(\lambda)) \wedge (|u| = |v|) \implies f(v) = f(u)$ then f has a multiplicative refinement.

The remaining ingredient is a theorem of Shelah which was stated as a constraint on goodness. However, the proof proceeds by defining countably many elements $\langle A_n : n < \omega \rangle$ of \mathcal{D}_* , and showing that the function $g : \mathcal{P}_{\aleph_0}(\mu) \rightarrow \mathcal{D}_*$ given by $g(s) = A_{|s|}$ does not have a multiplicative refinement. Since this function is uniform in the cardinality of s , the proof shows, albeit anachronistically, a failure of flexibility.

Fact 9.7. (See Shelah [20, Claim VI.3.23, p. 364].) *Let \mathcal{D} be a maximal filter modulo which \mathcal{G} is independent, $\kappa = CC(B(\mathcal{D}))$, for infinitely many $g \in \mathcal{G}$ $|\text{Range}(g)| > 1$ and $\mathcal{D}_* \supseteq \mathcal{D}$ an ultrafilter built by the method of independent families of functions. Then \mathcal{D}_* is not κ^+ -good. [More precisely, \mathcal{D}_* is not κ -flexible.]*

Observation 9.8. *Let $\mu < \lambda$ and let \mathcal{D} be a regular λ^+ -excellent filter on λ given by Theorem 8.1 in the case where $\mathbf{j}(\mathcal{P}(I)) = \mathfrak{B} = \mathfrak{B}_{2^\lambda, \mu}$. Then $B(\mathcal{D})$ has the μ^+ -c.c.*

Proof. Clearly $\mathfrak{B}_{2^\lambda, \mu}$ has the μ^+ -c.c. By definition of \mathbf{j} , whenever $\langle A_i : i < \kappa \rangle$ is a maximal disjoint set of nonzero elements of $B(\mathcal{D}) := \mathcal{P}(I)/\mathcal{D}$, we have $\mathbf{j}(A_i) \neq 0_{\mathfrak{B}}$, $\mathbf{j}(A_i) \cap \mathbf{j}(A_j) = 0_{\mathfrak{B}}$ for each $i < j < \kappa$ and thus $\langle \mathbf{j}(A_i) : i < \kappa \rangle$ is a pairwise disjoint set of nonzero elements in \mathfrak{B} . \square

Corollary 9.9. *Let $\mu < \lambda$ and let \mathcal{D} be a regular λ^+ -excellent filter on λ given by Theorem 8.1 in the case where $\mathbf{j}(\mathcal{P}(I)) = \mathfrak{B}_{2^\lambda, \mu}$. Then no ultrafilter extending \mathcal{D} built by the method of independent functions is λ -flexible.*

Proof. The translation is direct using Observation 9.8. For completeness, we justify compliance with the word “maximal” in Fact 9.7. In the language of Theorem 8.1, the filter \mathcal{D} is built as the union of an increasing sequence of filters \mathcal{D}_α , $\alpha < 2^\lambda$. For each α , $(I, \mathcal{D}_\alpha, (\mathcal{G}|\mathfrak{B}) \cup \mathcal{F}^\alpha)$ is a good triple, and $\mathcal{F}^{2^\lambda} = \emptyset$. Thus, by Fact 7.7, \mathcal{D} is maximal modulo which $\mathcal{G}|\mathfrak{B}$ remains independent. But by construction, $\mathcal{G}|\mathfrak{B}$ is isomorphic to \mathfrak{B} and thus to an independent family \mathcal{G}' of 2^λ functions each with domain λ (or I) and range μ . Letting \mathcal{G}' stand for \mathcal{G} in the statement of Fact 9.7 suffices. \square

Conclusion 9.10. *Let $\mu < \lambda$ and let \mathcal{D} be the regular λ^+ -excellent filter on λ given by Theorem 8.1 in the case where $\mathbf{j}(\mathcal{P}(I)) = \mathfrak{B}_{2^\lambda, \mu}$. Let $\mathcal{D}_* \supseteq \mathcal{D}$ be any ultrafilter constructed by the method of independent families of functions. Then M^λ/\mathcal{D}_* is not λ^+ -saturated whenever $\text{Th}(M)$ is non-simple or non-low.*

Proof. By Corollary 9.9 and Conclusion 9.5. \square

10. Lemmas for morality

Section 9 gave non-saturation by a cardinality argument (small c.c.). By [Theorem 6.13](#), this shifts the burden of saturation onto “morality” of an ultrafilter on \mathfrak{B} . Thus, in the next few sections of the paper, our aim is to show that there is an ultrafilter on $\mathfrak{B} = \mathfrak{B}_{2^\lambda, \mu}$, [Definition 7.8](#), which is moral for T_{rg} , the theory of the random graph. However, we build a somewhat more general theory.

The key inductive step in constructing that ultrafilter will be to find a multiplicative refinement for each possibility pattern. We do this essentially in two stages. First, in this section and the next we show that each such possibility pattern can be covered by μ approximations each of which has a multiplicative refinement. Second, we leverage these μ approximations to produce a multiplicative refinement for the original pattern.

We first state several results which indicate in what sense the random graph can be seen as “easier to saturate” than theories with more dividing.

Theorem D. (See [Engelking and Karłowicz \[5, Theorem 8, p. 284\]](#).) *Let $\mu \geq \aleph_0$. The Cartesian product of not more than 2^μ topological spaces each of which contains a dense subset of power $\leq \mu$ contains a dense subset of power $\leq \mu$.*

Proof (Sketch). Reduce to the case of identifying the dense subsets of the factors with discrete spaces on (at most) μ elements. [Theorem C](#) above guarantees the existence of an independent family $\mathcal{F} \subseteq {}^\mu \mu$ with $|\mathcal{F}| = 2^\mu$. Index the Cartesian product X by (a subset of) elements of this family, so $X = \prod_{f \in \mathcal{F}} X_f$ and let the function $\rho : \mu \rightarrow X$ be given by $\eta \mapsto \prod_{f \in \mathcal{F}} f(\eta)$. Then the condition that \mathcal{F} is independent says precisely that the image of ρ is dense in the product topology. \square

Note that the importance of “ $\mu \geq \aleph_0$ ” in [Theorem D](#) is for [Theorem C](#) and for the conclusion; in particular, there is no problem if the dense subsets of the factors are finite. Recall that T_{rg} is the theory of the random graph in the language $\{=, R\}$.

Fact 10.1. *If $\mu < \lambda \leq 2^\mu$, $A \subseteq \mathcal{C}_{T_{rg}}$, $|A| \leq \lambda$, then for some $B \subsetneq \mathcal{C}_{T_{rg}}$, $|B| = \mu$ we have that every nonalgebraic $p \in S(A)$ is finitely realized in B .*

Proof. By quantifier elimination, it suffices to consider $\Delta = \{xRy, \neg xRy\}$. Write the Stone space $S_\Delta(A)$ of nonalgebraic types as the product of λ -many discrete 2-element Stone spaces $S_\Delta(\{a\})$ and apply the previous theorem. The dense family of size μ given by the theorem is, in our context, a family of types, and since the monster model is λ^+ -saturated, we can realize each of them. Call the resulting set of realizations B . The hypothesis of density means precisely that each nonalgebraic type in $S(A)$ is finitely realized in B . \square

The next few facts simply restate these proofs in a different language.

Fact 10.2. *If $\mu < \lambda \leq 2^\mu$, we can find a set $A \subset B = \{\beta : \beta \in {}^\lambda 2\}$ so that $|A| \leq \mu$ and A is dense in B in the Tychonoff topology.*

Fact 10.3. *Let $\mu < \lambda \leq 2^\mu$, $\mathfrak{B} = \mathfrak{B}_{2^\lambda, \mu}$. Let $\mathfrak{B}_0 \subseteq \mathfrak{B} = \mathfrak{B}_{2^\lambda, \mu}$ be a Boolean subalgebra generated by λ independent partitions of \mathfrak{B} , see [Definition 7.12](#) above, and let \mathfrak{B}_1 be its completion in \mathfrak{B} . Then \mathfrak{B}_1 can be written as the union of μ ultrafilters.*

Observation 10.4. Let $\mu < \lambda \leq 2^\mu$. Let $\mathfrak{B} = \mathfrak{B}_{2^\lambda, \mu}$ or $\mathfrak{B} = \mathcal{P}(I)/\mathcal{D}$ where $(I, \mathcal{D}, \mathcal{G})$ is (λ, μ) -good. Let $\langle \mathbf{a}_u : u \in [\lambda]^{<\aleph_0} \rangle \subseteq \mathfrak{B} \setminus \{0_{\mathfrak{B}}\}$ be a sequence of elements of $\mathfrak{B} \setminus \{0_{\mathfrak{B}}\}$. Then there are a complete subalgebra \mathfrak{B}_1 of \mathfrak{B} and a sequence $\{\mathcal{E}_\epsilon : \epsilon < \mu\}$ of ultrafilters of \mathfrak{B}_1 so that

- for each $u \in [\lambda]^{<\aleph_0}$, \mathbf{a}_u is supported by \mathfrak{B}_1 , i.e. it is based on some partition of \mathfrak{B}_1 ,
- $\mathfrak{B}_1 \setminus \{0_{\mathfrak{B}}\}$ can be written as the union of these μ ultrafilters.

In particular, for each $u \in [\lambda]^{<\aleph_0}$ there is $\epsilon < \mu$ so that $\mathbf{a}_u \in \mathcal{E}_\epsilon$.

Proof. By [Observation 7.13](#) and [Fact 10.3](#). \square

Definition 10.5 (The key approximation property).

(Qr₀) Let Qr₀(T, φ, λ, μ) mean: T is a complete countable first-order theory, φ is a formula in the language of T , and $\lambda > \mu + |T|$.

(Qr₁) Let Qr₁(T, φ, λ, μ) mean: Qr₀(T, φ, λ, μ) and in addition if (A) then (B), where:

(A) Given

(i) $\mathfrak{B} = \mathfrak{B}_{2^\lambda, \mu}$ as in [Definition 7.8](#),

(ii) \mathcal{D}_* is an ultrafilter on \mathfrak{B} ,

(iii) $\bar{\mathbf{a}} = \langle \mathbf{a}_u : u \in [\lambda]^{<\aleph_0} \rangle$ is a $(\lambda, \mathfrak{B}, T, \varphi)$ -possibility with $u \in [\lambda]^{<\aleph_0} \implies \mathbf{a}_u \in \mathcal{D}_*$.

(B) We can find $\langle \mathcal{U}_\epsilon : \epsilon < \mu \rangle$ and $\langle \mathbf{b}_{u, \epsilon} : u \in [\mathcal{U}_\epsilon]^{<\aleph_0}, \epsilon < \mu \rangle$ so that:

(i) $\epsilon < \mu \implies \mathcal{U}_\epsilon \subseteq \lambda$, and $\bigcup \{\mathcal{U}_\epsilon : \epsilon < \mu\} = \lambda$,

(ii) $\langle \mathbf{b}_{u, \epsilon} : u \in [\mathcal{U}_\epsilon]^{<\aleph_0} \rangle$ is a multiplicative refinement of $\bar{\mathbf{a}}|_{[\mathcal{U}_\epsilon]^{<\aleph_0}}$, with each $b_{u, \epsilon} \in \mathfrak{B} \setminus \{0_{\mathfrak{B}}\}$,

(iii) if $\mathbf{b} \in \mathcal{D}_*$ and $u \in [\lambda]^{<\aleph_0}$ then for some $\epsilon < \mu$ we have $\mathbf{b}_{u, \epsilon} \wedge \mathbf{b} > 0$.

We write Qr₁(T, λ, μ) to mean that Qr₁(T, φ, λ, μ) for all φ in some critical set \mathcal{C}_T of formulas for T , or alternately for some critical set of possibility patterns, [Definition 6.14](#).

Observation 10.6. Suppose that:

- (1) \mathcal{D} is a regular, λ^+ -excellent filter on I ,
- (2) \mathcal{D}_1 is an ultrafilter on I extending \mathcal{D} ,
- (3) $\mathfrak{B} = \mathfrak{B}_{2^\lambda, \mu}$ is a Boolean algebra,
- (4) $\mathbf{j} : \mathcal{P}(I) \rightarrow \mathfrak{B}$ is a surjective homomorphism with $\mathcal{D} = \mathbf{j}^{-1}(\{1_{\mathfrak{B}}\})$,
- (5) $\varphi = \varphi(x, y)$ is a formula of T ,
- (6) $\mathcal{D}_* = \{\mathbf{b} \in \mathfrak{B} : \text{if } \mathbf{j}(A) = \mathbf{b} \text{ then } A \in \mathcal{D}_1\}$.

If (A) then (B) where:

(A) Qr₁(T, φ, λ, μ) holds in the case where \mathfrak{B} in [Definition 10.5](#) is replaced by the quotient Boolean algebra $\mathcal{P}(I)/\mathcal{D}$,

(B) Qr₁(T, φ, λ, μ).

Proof. By the Transfer [Lemma 6.12](#). \square

Observation 10.7. The set $\{\varphi(x; y, z, w) = (z = w \implies xRy) \wedge (z \neq w \implies \neg xRy)\}$ is a critical set of formulas for the theory of the random graph. Moreover, consistency of any set S of instances of φ follows from consistency of all 2-element subsets of S .

Proof. By quantifier elimination, since all algebraic types will be automatically realized in regular ultrapowers. \square

Convention 10.8. We will informally write instances of the formula from [Observation 10.7](#) as $\varphi(x; a, \mathbf{t})$ where $\mathbf{t} \in \{0, 1\}$ is the truth value of $z = w$.

Lemma 10.9. *Let T be the theory of the random graph and φ the formula from [Observation 10.7](#). Then $\text{Qr}_1(T, \varphi, \lambda, \mu)$, thus $\text{Qr}_1(T, \lambda, \mu)$.*

Proof. Let \mathcal{D}_* be an ultrafilter on \mathfrak{B} and let $\bar{\mathbf{a}} = \langle \mathbf{a}_u : u \in [\lambda]^{<\aleph_0} \rangle$ be a $(\lambda, \mathfrak{B}, T, \varphi)$ -possibility satisfying (A) of [Definition 10.5](#).

It will suffice to prove [Observation 10.6\(A\)](#), thus we work in that setting, i.e. a reduced product where \mathcal{D} is an excellent filter on I and $\mathcal{P}(I)$ admits a homomorphism \mathbf{j} to \mathfrak{B} with $\mathbf{j}^{-1}(\{1_{\mathfrak{B}}\}) = \mathcal{D}$. Let M be a fixed model of the random graph. By the Transfer Theorem, we may associate to $\bar{\mathbf{a}}$ the (weak) distribution of a nonalgebraic type

$$p = \{\varphi(x; a_i, \mathbf{t}_i) : i < \lambda\}$$

so that the elements a_i belong to ${}^I M$ and $\mathbf{t}_i \in \{0, 1\}$. We will give a series of definitions and assertions.

Step 0: A supporting subalgebra. Apply [Observation 10.4](#) to choose a complete subalgebra \mathfrak{B}_1 of \mathfrak{B} and $\langle \mathcal{E}'_\epsilon : \epsilon < \mu \rangle$ a covering sequence of ultrafilters. In what follows, we denote by $X(\mathfrak{B}_1)$ the set $\{x_{\alpha, \epsilon} : \alpha < \lambda, \epsilon < \mu\}$ of generators of \mathfrak{B}_1 . Note that each element of $\bar{\mathbf{a}}$ is supported on a partition whose elements are finite intersections of elements of $X(\mathfrak{B}_1)$.

Denote by $Y(\mathfrak{B}_1)$ the set of nonempty finite intersections of elements of $X(\mathfrak{B}_1)$, where “ \mathbf{y} is nonempty” means $\mathfrak{B} \models \mathbf{y} \neq 0$. This set is the direct analogue of $\text{Fin}_s(\mathcal{G})$ in the case where functions $g_\alpha \in \mathcal{G}$ correspond to $\{x_{\alpha, \epsilon} : \epsilon < \mu\}$.

Step 1: The collision function F_ϵ . For each $\epsilon < \mu$, define a partial function F_ϵ from λ to λ as follows. Let $F_\epsilon(i) = j$ if there is some $\mathbf{c}_h \in Y(\mathfrak{B}_1)$ which witnesses this, which means:

- (α) $\mathbf{c}_h \in \mathcal{E}'_\epsilon$,
- (β) $\mathfrak{B} \models \{s \in I : a_i[s] = a_j[s]\} \geq \mathbf{c}_h$,
- (γ) if $j_1 < j$ then $\mathfrak{B} \models \{s \in I : a_i[s] = a_{j_1}[s]\} \wedge \mathbf{c}_h = 0$.

Note that in condition (β) we may ask that “ $\mathbf{a}_{\{i\}} \wedge \mathbf{a}_{\{j\}} \wedge \{s \in I : a_i[s] = a_j[s]\} \geq \mathbf{c}_h$ ”. However this is redundant here as $\bar{\mathbf{a}}$ is a possibility pattern for the random graph, i.e. by choice of φ , $\mathfrak{B} \models \mathbf{a}_u = 1$ whenever $|u| = 1$.

Note also that for any ϵ and i there is at most one such j . (If not, let j_1, \mathbf{c}_{h_1} and j_2, \mathbf{c}_{h_2} be two distinct values given with their associated witness sets, and notice that $\mathbf{c}_{h_1} \wedge \mathbf{c}_{h_2}$ witnesses both as \mathcal{E}'_ϵ is a filter, contradicting (γ) by the linear ordering of λ .) Furthermore, $F_\epsilon(i) \leq i$.

For the remainder of the argument, let $\mathbf{c}_{h_{\epsilon, i}}$ witness $F_\epsilon(i) = j$.

Step 2: ‘Injectivity’ of F_ϵ . If $i_1 \neq i_2$ are from $\text{dom}(F_\epsilon)$ and $j_1 = F_\epsilon(i_1)$, $j_2 = F_\epsilon(i_2)$ then

$$\mathfrak{B} \models \{s \in I : a_{i_1}[s] = a_{i_2}[s]\} \wedge (\mathbf{c}_{h_{\epsilon, i_1}} \wedge \mathbf{c}_{h_{\epsilon, i_2}}) = 0.$$

If not, let $j = \min\{j_1, j_2\}$; then $j, \mathbf{c}_{h_{\epsilon, i_1}} \wedge \mathbf{c}_{h_{\epsilon, i_2}}$ contradicts Step 1 for one of the two values of i . (If $j_1 = j_2$, then $\mathbf{c}_{h_{\epsilon, i_1}} \wedge \mathbf{c}_{h_{\epsilon, i_2}} \in \mathcal{E}_\epsilon$ contradicts $i_1 \neq i_2 \pmod{\mathcal{E}_\epsilon}$.)

Step 3: The family of approximations, before re-indexing. Let

$$\mathcal{U}_{\epsilon, \zeta} = \{i < \lambda: i \in \text{dom}(F_\epsilon) \text{ and } \mathbf{t}_i = f_\zeta(F_\epsilon(i))\}.$$

Roughly speaking, we choose only the formulas $\varphi(x; a_i)^{t_i}$ in the type whose parameter a_i collides modulo \mathcal{E}_ϵ (as recorded by F_ϵ) with an element whose instance in the type has the same exponent (when filtered through f_ζ , an element of the dense family of functions).

In Step 6 we will re-index the double subscript (ϵ, ζ) but for now it is a little more transparent to leave it as a pair. Note that neither \mathcal{E}_ϵ nor any of the sets $\mathbf{c}_{h_{\epsilon, i}}$ depend on ζ .

Step 4: The multiplicative refinements. For each $\mathcal{U}_{\epsilon, \zeta}$ from Step 3, and $u \in [\mathcal{U}_{\epsilon, \zeta}]^{< \aleph_0}$, let $\mathbf{b}_{\epsilon, u} = \bigwedge_{i \in u} \mathbf{c}_{h_{\epsilon, i}}$. Let us verify that

$$\{\mathbf{b}_{\epsilon, u}: u \in [\mathcal{U}_{\epsilon, \zeta}]^{< \aleph_0}\}$$

is indeed a multiplicative refinement of $\bar{\mathbf{a}}|_{[\mathcal{U}_{\epsilon, \zeta}]^{< \aleph_0}}$.

Since all of the $h_{\epsilon, i}$ are from $Y(\mathfrak{B}_1)$ and $h_{\epsilon, i} \in \mathcal{E}_\epsilon$, none of these intersections is empty mod \mathcal{D} (in fact, they belong to \mathcal{E}_ϵ) and the assignment is multiplicative. Let us verify that it refines the original sequence. By [Observation 10.7](#), it suffices to check $|u| \leq 2$. The case $|u| = 1$ follows by Step 1. Suppose then that $u = \{i, j\}$. By Step 2 and the choice of $\mathcal{U}_{\epsilon, \zeta}$, whenever $u \in [\mathcal{U}_{\epsilon, \zeta}]^{< \aleph_0}$ we have that

$$\mathfrak{B} \models \text{“}\mathbf{b}_{u, \epsilon} \wedge \{s \in I: a_i[s] = a_j[s], \mathbf{t}_i \neq \mathbf{t}_j\} = 0\text{”}.$$

By choice of φ and the fact that $\bar{\mathbf{a}}$ is a possibility pattern, it must be that $\mathfrak{B} \models \text{“}\mathbf{b}_{u, \epsilon} \leq \mathbf{a}_u\text{”}$ as desired. (That is, inconsistency in the random graph can only arise from equality.)

Step 5: Covering the type. In this step we show that the sequence of approximations covers the type, i.e.

$$[\lambda]^{< \aleph_0} = \bigcup \{[\mathcal{U}_{\epsilon, \zeta}]^{< \aleph_0}: \epsilon < \mu, \zeta < \mu\}.$$

Let $u \in [\lambda]^{< \aleph_0}$ be given, and let $\{i_\ell: 0 < \ell \leq n\}$ list u .

Informally, we find a set on which the given n -tuple is distinct and on which the collision function is well defined. This set will belong to some \mathcal{E}_ϵ by [Observation 10.4](#), and by construction its image under F_ϵ is as desired. We then need to choose ζ corresponding to the correct pattern of positive and negative instances, which we can do by [Fact 10.2](#).

More formally, let $\mathbf{x}_u = \{s: \bigwedge_{0 < \ell < k < n} a_{i_\ell}[s] \neq a_{i_k}[s]\}$ be the set on which all parameters are distinct, and note that $\mathbf{x}_u \in \mathcal{D}_*$, so in particular is not $0_{\mathfrak{B}}$. Choose $\mathbf{y}_{h_\ell} \in Y(\mathfrak{B}_1)$, $j_\ell \in \lambda$ by induction on ℓ , $1 \leq \ell \leq n$ as follows:

- Choose h_0 so that $\mathbf{y}_{h_0} \subseteq \mathbf{x}_u \pmod{\mathcal{D}}$.
- For $\ell = m + 1 \leq n$, choose $\mathbf{y}_{h_\ell}, j_\ell$ so that $\mathbf{y}_{h_\ell} \leq \mathbf{y}_{h_m}$ and

$$\{s: a_{i_m}[s] = a_{j_m}[s]\} \supseteq \mathbf{x}_{h_\ell} \text{ and for no } j < j_\ell \text{ is } \{s: a_{i_m}[s] = a_j[s]\} \wedge \mathbf{x}_{h_\ell} \neq 0_{\mathfrak{B}}.$$

Let $\epsilon < \mu$ be so that $\mathbf{y}_{h_n} \in \mathcal{E}_\epsilon$ (which we can do by the choice of $\langle \mathcal{E}_\epsilon: \epsilon < \mu \rangle$). Note that \mathbf{y}_{h_n} witnesses $F_\epsilon(i_\ell) = j_\ell$ for $0 < \ell \leq n$. Also, by choice of \mathbf{y}_{h_0} , we have that on \mathbf{y}_{h_n} , $\langle j_\ell: 0 < \ell \leq n \rangle$

has no repetitions. So as we chose the sequence of functions $\langle f_\zeta : \zeta < \mu \rangle$ to be dense, there is $\zeta < \mu$ so that

$$\bigwedge_{0 < \ell \leq n} f_\zeta(j_\ell) = \mathbf{t}_{i_\ell}.$$

Now $\mathcal{U}_{\epsilon, \zeta}$ is as required.

Step 6: Re-indexing. For notational alignment with [Definition 10.5](#), re-index this family of triples by $\epsilon < \mu$.

Step 7: Largeness. Finally, we verify that if $\mathbf{b}_* \in \mathcal{D}_*$ and $u \in [\lambda]^{<\aleph_0}$ then for some $\epsilon < \mu$ we have $\mathbf{b}_{u, \epsilon} \wedge \mathbf{b}_* > 0$.

Note that \mathbf{a}_u and \mathbf{b}_* both belong to \mathcal{D}_* . As \mathfrak{B}_1 supports $\bar{\mathbf{a}}$ and \mathcal{D}_* is an ultrafilter on \mathfrak{B}_1 , we may find \mathbf{x} so that $\mathfrak{B}_1 \models "0 < \mathbf{x} \leq (\mathbf{a}_u \wedge \mathbf{b}_*)"'$. Since the sequence $\langle \mathcal{E}_\epsilon : \epsilon < \mu \rangle$ was chosen to cover $\mathfrak{B}_1 \setminus 0_{\mathfrak{B}}$, choose $\epsilon_* < \mu$ so that $\mathbf{x} \in \mathcal{E}_{\epsilon_*}$. Note that we may choose ϵ_* so that in addition, $u \subseteq \mathcal{U}_\epsilon$ (since the re-indexing in Step 6 amounted to absorbing the additional parameter ζ). Then $\mathbf{b}_{u, \epsilon}$ is nonzero and intersects \mathbf{x} , as they are both members of \mathcal{E}_ϵ . This completes the proof. \square

Discussion 10.10. Two properties of the random graph which make this proof more transparent are first, that the question of whether a given distribution is consistent relies only on the pattern of incidence in the parameters, and second, this pattern does not admit too many inconsistencies (dividing, or long chains in the Boolean algebra) as described in [Fact 10.1](#) and its translation [10.2](#).

The class of theories in which consistency of distribution relies only on incidence is quite rich. They were studied and classified in Malliaris [\[14\]](#), where it was shown that any such theory is dominated in the sense of Keisler's order either by the empty theory, by the random graph or by the minimum TP_2 theory, i.e. the model completion T_{feq}^* of a parametrized family of cross-cutting equivalence relations. (Such theories have intrinsic interest, corresponding naturally to independence properties, and to assertions about second-order structure on ultrapowers; in fact, the classification applied the second author's proof that there are only four second-order quantifiers.) It is clear from this result why "consistency of distribution relies only on incidence" is not enough to guarantee that the proof of [Lemma 10.9](#) goes through. In particular, the minimum TP_2 theory would allow us to carry out the part of the proof of [Lemma 10.9](#) which had to do with distributing elements so their collisions are controlled by the functions F_ϵ , but [Fact 10.1](#) would no longer apply due to the amount of dividing, and the corresponding functions of [Fact 10.2](#) would thus need a larger domain (larger than μ) to properly code all possible types. Since any ultrafilter which saturates the minimum TP_2 theory T_{feq}^* is flexible, as discussed in [Section 2](#), the main theorem of this paper shows that the distinction between the random graph-dominated theories and the T_{feq} -dominated theories is indeed sharp.

11. The moral ultrafilter

In this section we construct an ultrafilter \mathcal{D}_* on $\mathfrak{B}_{2^\lambda, \mu}$ which is moral for any Qr_1 theory, and in particular for the theory of the random graph. Note that the random graph is minimum in Keisler's order among the unstable theories, see [\[15, §4\]](#).

Theorem 11.1. *Suppose $\mu < \lambda \leq 2^\mu$ and let $\mathfrak{B} = \mathfrak{B}_{2^\lambda, \mu}$. Then there is an ultrafilter \mathcal{D}_* on \mathfrak{B} which is moral for all countable theories T so that $\text{Qr}_1(T, \lambda, \mu)$. In particular, \mathcal{D}_* is moral for all countable stable theories and for the theory of the random graph.*

Proof. We first prove the “in particular” clause. Any such ultrafilter \mathcal{D}_* will be moral for the random graph by [Lemma 10.9](#) above. Moreover, any unstable theory (so in particular the random graph) is strictly above the stable theories in Keisler’s order, see [[20, Theorem VI.0.3, p. 323](#)]. Thus by [Theorem 6.13](#), any \mathcal{D}_* moral for the random graph must be moral for countable stable theories as well.

In the remainder of the proof, we construct the ultrafilter \mathcal{D}_* .

Step 1: Setup for inductive construction of \mathcal{D}_ .* We now build the ultrafilter \mathcal{D}_* . Enumerate the generators of \mathfrak{B} as $\langle \mathbf{x}_{\alpha,\epsilon} : \alpha < 2^\lambda, \epsilon < \mu \rangle$ in the notation of [Definition 7.8](#). Let $\langle \bar{\mathbf{a}}_\alpha : \alpha < 2^\lambda \rangle$ be an enumeration of all relevant $(\lambda, \mathfrak{B}, T)$ -possibilities, with each possibility occurring 2^λ -many times. [On counting: Note that there are, up to renaming of symbols, at most continuum many complete countable theories, so at most continuum many theories so that $\text{Qr}_1(T, \lambda, \mu)$. Moreover, since we may identify the possibility patterns with sequences from $\mathcal{P}_{\aleph_0}(\lambda)$ into \mathfrak{B} , $|\mathfrak{B}| = 2^\lambda$ there are no more than 2^λ patterns for each theory.]

We build by induction on $\alpha < 2^\lambda$ a continuous increasing sequence of filters \mathcal{D}_α of \mathfrak{B} and a continuous decreasing sequence of independent partitions \mathcal{G}^α satisfying the following conditions.

- (1) $\beta < \alpha < 2^\lambda$ implies $\mathcal{D}_\beta \subseteq \mathcal{D}_\alpha$ are filters on \mathfrak{B} ,
- (2) α limit implies $\mathcal{D}_\alpha = \bigcup \{ \mathcal{D}_\beta : \beta < \alpha \}$,
- (3) $\beta < \alpha < 2^\lambda$ implies $\mathcal{G}^\alpha \subseteq \mathcal{G}^\beta \subseteq \mathcal{G}$,
- (4) $\alpha < 2^\lambda$ implies $|\mathcal{G}^\alpha| = 2^\lambda$,
- (5) α limit implies $\mathcal{G}^\alpha = \bigcap \{ \mathcal{G}^\beta : \beta < \alpha \}$,
- (6) $\alpha = \beta + 1$ implies that if $\bar{\mathbf{a}}_\beta$ is a sequence of elements of \mathcal{D}_β then there is a multiplicative refinement $\bar{\mathbf{b}}$ of $\bar{\mathbf{a}}_\beta$ consisting of elements of \mathcal{D}_α ,
- (7) $\alpha < 2^\lambda$ implies that $(\mathfrak{B}, \mathcal{D}_\alpha, \mathcal{G}^\alpha)$ is a $(2^\lambda, \mu)$ -good Boolean triple,
- (8) $\mathcal{D}_* = \mathcal{D}_{2^\lambda} = \bigcup \{ \mathcal{D}_\alpha : \alpha < 2^\lambda \}$.

For the case $\alpha = 0$, let $\mathcal{D}_0 = \{1_{\mathfrak{B}}\}$, $\mathcal{G} = \{ \{ \mathbf{x}_{\alpha,\epsilon} : \epsilon < \mu \} : \alpha < 2^\lambda \}$ be the set of generators of \mathfrak{B} from [Definition 7.8](#).

The limit cases are uniquely determined by the inductive hypotheses (2), (8), and consistent by (the direct translation of) [Fact 7.7](#) above.

Step 2: The successor stage. Thus the only nontrivial point is the case $\alpha = \beta + 1$. Let $\bar{\mathbf{a}}_\beta$ be given, and suppose that $u \in [\lambda]^{<\aleph_0} \implies \mathbf{a}_u \in \mathcal{D}_\beta$; if not, choose \mathcal{D}_α to satisfy condition (4) and continue to the next step.

Noting that we have assumed $u \in [\lambda]^{<\aleph_0} \implies \mathbf{a}_u \in \mathcal{D}_\beta$, let $\mathcal{D}_* \supseteq \mathcal{D}_\beta$ be any ultrafilter on \mathfrak{B} (thus on \mathfrak{B}_β). Then we may apply [Definition 10.5\(A\)](#) with $\bar{\mathbf{a}}$, \mathcal{D}_* , and \mathfrak{B}_β in place of \mathfrak{B} .

Let $\langle \mathcal{U}_\epsilon : \epsilon < \mu \rangle$ and $\langle \mathbf{b}_{u,\epsilon} : u \in [\mathcal{U}_\epsilon]^{<\aleph_0}, \epsilon < \mu \rangle$ be the objects returned by [Definition 10.5\(B\)](#). By [Definition 10.5\(B\)\(ii\)](#), for each $\epsilon < \mu$ and $u \in [\mathcal{U}_\epsilon]^{<\aleph_0}$, we have that $\mathbf{b}_{u,\epsilon} \in \mathcal{D}^+$, i.e. $\neq \emptyset \pmod{\mathcal{D}}$.

Let $W_\beta = \{ \mathbf{a}_u : u \in [\lambda]^{<\aleph_0} \} \cup \{ \mathbf{b}_{u,\epsilon} : u \in [\mathcal{U}_\epsilon]^{<\aleph_0}, \epsilon < \mu \}$. Since these are all \mathcal{D} -nonempty sets, apply [Observation 7.13](#) to obtain $\mathcal{G}' \subseteq \mathcal{G}^\beta$ so that $|\mathcal{G}'| \leq \lambda$ and each element of W_β is supported in $\text{Fin}_s(\mathcal{G}')$.

Let $g_\gamma = \{ \mathbf{x}_{\gamma,\epsilon} : \epsilon < \mu \}$ be any element of $\mathcal{G}^\beta \setminus \mathcal{G}'$. Let $\mathcal{G}^\alpha = \mathcal{G}^\beta \setminus (\mathcal{G}' \cup \{g_\gamma\})$.

Now we define the proposed multiplicative refinement. For each $u \in [\lambda]^{<\aleph_0}$, define

$$\mathbf{b}_u = \bigcup \{ x_{\gamma,\epsilon} \cap \mathbf{b}_{u,\epsilon} : \epsilon < \mu \}.$$

Let $\bar{\mathbf{b}} = \langle \mathbf{b}_u : u \in [\lambda]^{<\aleph_0} \rangle$. We verify that it is multiplicative:

$$\begin{aligned} \mathbf{b}_u \cap \mathbf{b}_v &= \bigcup \{ \mathbf{x}_{\gamma, \epsilon} \cap \mathbf{b}_{u, \epsilon} : \epsilon < \mu \} \cap \bigcup \{ \mathbf{x}_{\gamma, \epsilon} \cap \mathbf{b}_{v, \epsilon} : \epsilon < \mu \} \\ &= \bigcup \{ \mathbf{x}_{\gamma, \epsilon} \cap (\mathbf{b}_{u, \epsilon} \cap \mathbf{b}_{v, \epsilon}) : \epsilon < \mu \} \quad \text{as each approximation is multiplicative} \\ &= \bigcup \{ \mathbf{x}_{\gamma, \epsilon} \cap (\mathbf{b}_{u \cup v, \epsilon}) \} \\ &= \mathbf{b}_{u \cup v}. \end{aligned}$$

We now show these sets generate a filter which retains enough independence to satisfy (7). Let $u \in [\lambda]^{<\aleph_0}$ be given. Since $\langle \mathbf{b}_u : u \in [\lambda]^{<\aleph_0} \rangle$ is monotonic, and since, as remarked above, each $\mathbf{b}_u \neq \emptyset \bmod \mathcal{D}_\beta$, the set $\mathcal{D}_\beta \cup \{ \mathbf{b}_u : u \in [\lambda]^{<\aleph_0} \}$ generates a filter which we call \mathcal{D}'_α .

Let $A_{h'} \in \text{Fin}_s(\mathcal{G}^\alpha)$. By choice of \mathcal{G}' , there is a nonzero $A_h \in \text{Fin}_s(\mathcal{G}')$ so that $\mathfrak{B} \models "A_h \leq \mathbf{b}_{u, \epsilon}"$. By the inductive hypothesis of independence (7), since \mathcal{G}' , $\{g_\gamma\}$, \mathcal{G}^α have pairwise empty intersection,

$$\mathfrak{B} \models " \mathbf{b}_{u, \epsilon} \supseteq A_h \cap A_{h'} \cap \mathbf{x}_{\gamma, \epsilon} \neq \emptyset ".$$

We have shown that $(\mathfrak{B}, \mathcal{D}'_\alpha, \mathcal{G}^\alpha)$ is a pre-good Boolean triple. Without loss of generality, extend \mathcal{D}'_α to a filter \mathcal{D}_α so that $(\mathfrak{B}, \mathcal{D}_\alpha, \mathcal{G}^\alpha)$ is a good Boolean triple. This completes the successor stage.

Step 3: Finish. Note that \mathcal{D}_* will be an ultrafilter, and likewise \mathcal{G}^{2^λ} will be empty by [Fact 7.7](#), as explained at the beginning of this section. This completes the proof. \square

12. The dividing line

Theorem 12.1. *Let $\mu < \lambda \leq 2^\mu$. Then there is a regular ultrafilter \mathcal{D} on λ so that:*

- (1) *for any countable theory T so that $\text{Qr}_1(\lambda, \mu, T)$ and $M \models T$, M^λ/\mathcal{D} is λ^+ -saturated,*
- (2) *in particular, when T is stable or T is the theory of the random graph, M^λ/\mathcal{D} is λ^+ -saturated,*
- (3) *for any non-low or non-simple theory T and $M \models T$, M^λ/\mathcal{D} is not λ^+ -saturated.*

Thus there is a dividing line in Keisler's order among the simple unstable theories.

Proof. By [Theorem 6.13](#), the construction problem separates into a problem of excellence and a problem of morality.

By [Theorem 8.1](#) there is a λ -regular, λ^+ -excellent filter \mathcal{D}_0 on λ which admits a surjective homomorphism $\mathbf{j} : \mathcal{P}(I) \rightarrow \mathfrak{B} = \mathfrak{B}_{2^\lambda, \mu}$ so that $\mathcal{D}_0 = \mathbf{j}^{-1}(\{1_{\mathfrak{B}}\})$.

By [Theorem 11.1](#) there is an ultrafilter \mathcal{D}_* on $\mathfrak{B}_{2^\lambda, \mu}$ which is moral for any countable theory T so that $\text{Qr}_1(T, \lambda, \mu)$.

Now let \mathcal{D} be $\{\mathbf{j}^{-1}(\mathbf{b}) : \mathbf{b} \in \mathcal{D}_*\}$. Then \mathcal{D} is an ultrafilter and is regular as it extends \mathcal{D}_0 . \mathcal{D} satisfies conditions (1) and (2) by [Theorems 11.1 and 6.13](#), and \mathcal{D} satisfies condition (3) by [Conclusion 9.10](#). This completes the proof. \square

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